

# Tabhaigh East, Lewis and Harris

## Hydrographic Data Report: Deployment ID436

### 29<sup>th</sup> February to 29<sup>th</sup> May 2024

July 2024  
Mowi Scotland Limited

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**QUALITY ASSURANCE**

Mowi Scotland Ltd is ISO9001 and ISO14001 accredited and all project management follows policies designed to ensure that the collection, collation and reporting of information produced in the course of our operations is done to a consistently high standard meeting the requirements of the end user.

# 1. Introduction

Mowi Scotland Ltd. is preparing an application to the Scottish Environmental Protection Agency (SEPA) for a new salmon farm site located at Tabhaigh East, at the mouth of Loch Erisort. Mowi Scotland Ltd. propose 8 x 160 m circumference pens, with 15 m and 20 m deep nets, held in a 100 m grid (Figure 1).

Mowi Scotland Ltd. have carried out hydrographic surveys at the site in 2023 and 2024. Hydrographic data at Tabhaigh East was gathered during this time in two deployments:

- i. 28<sup>th</sup> June 2023 to 5<sup>th</sup> October 2023 (ID420)
- ii. 29<sup>th</sup> February 2024 to 29<sup>th</sup> May 2024 (ID436)

The purpose of this report is to assess the suitability of the collected hydrographic data during 29<sup>th</sup> February 2024 to 29<sup>th</sup> May 2024 (ID436) for calibration of a hydrodynamic model of the East of Lewis and Harris region and input into the NewDepomod model.

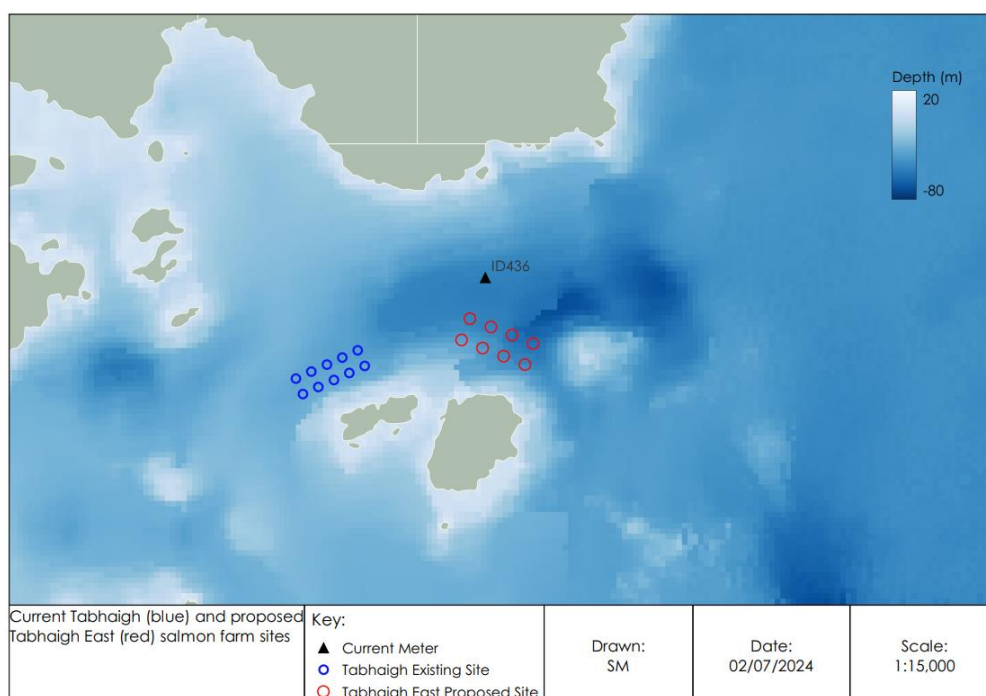


Figure 1. Proposed layout for Tabhaigh East including bathymetry in relation to the existing Tabhaigh site. The current meter deployment location is marked by the black triangle.

## 2. Materials & Methods

### 2.1 Bathymetry

Bathymetry for the study area was taken from the UKHO INSPIRE bathymetry data (<http://aws2.caris.com/ukho/mapViewer/map.action>), supplemented by a local bathymetry survey which took place at the site in July 2023.

### 2.2 Current Data

Mowi staff carried out a hydrographic survey at the site in 2024. The purpose of this hydrographic report is to assess the suitability of the collected hydrographic data for use with the NewDepomod and

Hydrodynamic models. The data contained in this report were recorded at the site from 29<sup>th</sup> February 2024 to 29<sup>th</sup> May 2024 (89 days and 14 hours of data; deployment ID436).

The Sentinel V100 (Wide) ADCP (Table 1), within its mooring frame, was positioned at 58.12538N, - 6.37873W (142285E 923535N), which was approximately 520 m from the nearest shoreline and approximately 280 m from the centre of the proposed cage group (Figure 1). The transducer head was 70 cm from the base of the mooring frame. The mean depth (derived from the pressure sensor) at the Sentinel V100 ADCP position was 66.58 m.

Initial soundings were taken to establish the possible depth the Sentinel V100 ADCP would be situated at during high tide and so that the most appropriate cell size could be determined. The cell size was set at 1.0 m and the number of cells to 44.

Data was automatically written and stored to the internal memory within the Sentinel V100 ADCP main body and then downloaded to computer after completion of the deployment period via WiFi.

### *2.3 Magnetic Variation*

No magnetic variation correction was made to the Sentinel V100 ADCP during deployment, this was undertaken to the data after the instrument was recovered and data downloaded. The magnetic variation used was -2.88°; this was determined using the World Magnetic Model, produced jointly with the US National Oceanographic and Atmospheric Administration's National Geophysical Data center. Further details can be found at <http://www.geomag.bgs.ac.uk/navigation.html>

### *2.4 Data Processing*

Upon retrieval of the Sentinel V100 ADCP current meter, all data was downloaded to a computer for analysis. The raw data file was opened in Teledyne's "Velocity" software and Matlab. Deployment diagnostic data (beam intensity, correlation, pitch and roll) were analysed to confirm that the deployment was successful with the instrument orientated upright. The heading data were also examined to identify any movement of the Sentinel V100 ADCP mooring frame during the deployment.

The diagnostic data suggested that velocities from the first 54 bins were valid (Figure 2). Calculations were undertaken to identify the cells to be used for surface and middle currents. Surface data was taken at an average depth (derived from the pressure sensor) of 7.01 m (cell 54), and cage-bottom data at 15.01 m (cell 46). Surface and middle cell heights were 56.71 m and 48.71 m from the seabed respectively. The bottom cell (cell 1) was at a depth of 60.01 m and 3.71 m above the seabed.

Table 1: Sentinel V100 ADCP Specifications.

Depth Cell Size <sup>1</sup>	V20 (1000kHz)		V50 (500kHz)		V100 (300kHz)		
	Depth Cell Size <sup>1</sup>	Range (m) <sup>2,3</sup> Wide/Narrow	Std Dev (cm/s) <sup>3,4</sup> Wide/Narrow	Range (m) <sup>2,3</sup> Wide/Narrow	Std Dev (cm/s) <sup>3,4</sup> Wide/Narrow	Range (m) <sup>2,3</sup> Wide/Narrow	Std Dev (cm/s) <sup>3,4</sup> Wide/Narrow
	0.25m	18.0/22.6	19.2/36.5				
	0.3m	19.3/24.0	11.1/20.8				
	0.5m	20.2/24.9	7.1/13.4	44.1/57.6	19.2/36.5		
	1.0m	22.1/26.9	3.6/6.7	50.5/64.6	7.1/13.5	94.5/120.6	10.9/20.6
	2.0m	24.5/29.4	1.7/3.2	56.0/70.6	3.6/6.7	103.5/130.4	5.5/10.3
	4.0m	26.9/32.0	0.8/1.6	63.1/78.2	1.7/3.2	114.6/142.3	2.7/5.2
	6.0m			67.4/82.8	1.1/2.1	121.7/151.5	1.8/3.3
<b>Communications and Recording</b>	Wireless Internal memory	802.11b/g/n One 16GB Micro SD Card included					
<b>Profile Parameters</b>	Velocity accuracy  Velocity resolution Velocity range Ping rate	V20/V50: 0.3% of the water velocity relative to the ADCP ±0.3cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s 0.1cm/s ±5m/s (default); ±20m/s (maximum) Up to 4Hz					
<b>Echo Intensity Profile</b>	Vertical resolution Dynamic range Precision	Depth cell size 80dB ±1.5dB					
<b>Transducer and Hardware</b>	Beam angle Configuration Depth rating Materials	25° 4-beam, convex; 5th beam vertical 200m Transducer, housing, and end cap: plastic Connector: metal shell					
<b>Standard Sensors</b>	Temperature (mounted on transducer) Compass (magneto-inductive sensor) Tilt (MEMS accelerometers)  Pressure sensor (mounted on transducer)	Range -5° to 45°C, precision ±0.4°C, resolution 0.1° Accuracy 2° RMS, resolution 0.1°, max. dip angle 85° Pitch range ±90°, roll range ±180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS					
<b>Power</b>	External DC input Internal battery voltage Battery capacity; over-the-counter @0°C Battery pack @5°C	12–20VDC 18VDC new 100 watt hours (typical) 510 watt hours					
<b>Software</b>	Teledyne RDI's new software included	ReadyW—Pre-deployment (testing, planning, and data recovery) <sup>5</sup> Velocity—Post-processing (data handling, display, and export) <sup>6</sup>					
<b>Environmental</b>	Standard depth rating Operating temperature Storage temperature (without batteries) Weight in air Weight in water	200m -5° to 45°C -30° to 60°C 7.5kg – 16.0kg 1.6kg – 6.0kg					
<b>Available Options</b>	External battery case • AC/DC power converter • 5th beam (at time of order only) • Waves processing • Straight or right-angle metal shell connector						
<b>Dimensions</b>	Special configuration drawing available upon request						

1. User's choice of depth cell not limited to the typical values specified.  
2. Ranges specified are typical at temperature of 5°C and salinity of 35psu; longer ranges are possible.  
3. User selects the bandwidth mode; wide = 25% or narrow = 6%.  
4. Standard deviations (Std Dev) are typical values for single ping data.  
5. Resident in ADCP accessed via a web browser.  
6. Windows™ based software program.

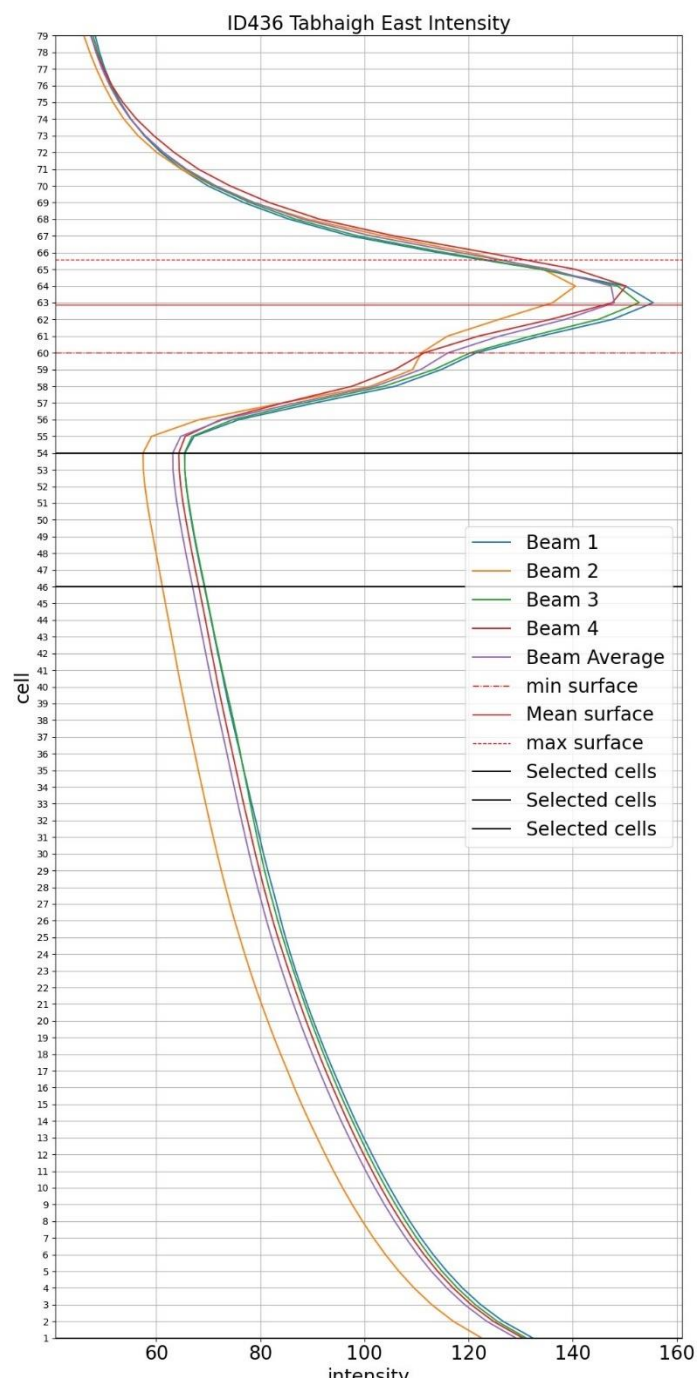


Figure 2. Mean intensity of the ADCP signal for the ID436 dataset plotted by bin number

The ‘first cell range’ is automatically calculated by the instrument, which is the distance from the transducer head to the first cell. For this deployment, the first cell range was calculated as 3.01 m. This value is then added to the height of the instrument frame (0.7 m) to get the first cell height above the seabed, which equated to 3.71 m

Standard deviation has been assessed throughout the deployment to identify accurate and reliable data for near bed, middle (net depth) and surface cells using the following equation:

$$Cell\ StdDev = \frac{Instrument\ StdDev}{\sqrt{No.\ valid\ pings}} \quad (1)$$

The Instrument Standard Deviation (StdDev) in Equation 1 is determined using the deployment settings when the meter is programmed, examples of the StdDev values for different configurations are shown in Table 1. This deployment had a cell size of 1m which equates to an Instrument StdDev of 10.9 cm/s.

The Percentage of valid pings used to calculate Cell StdDev is derived using “Percentage Good” data which allows us to relate the StdDev to the actual data gathered. The percent good data is available for 1, 2, 3 and 4 beams which represent the following:

- Percent good 1 = % of good data computed from 3 Beams
- Percent good 2 = % of bad data due to more than 2 Beam bad
- Percent good 3 = % of bad data due to error velocity exceeded
- Percent good 4 = % of good data computed from 4 Beams

The method described has been used to calculate the Standard deviation throughout the deployment for the surface, middle and bottom cells; the average StdDev values for the surface, middle and bottom was 0.63cm/s, 0.63cm/s and 0.63cm/s respectively which are all within the SEPA criteria of 2cm/s.

### 2.5 Meteorological Data

*The collection of meteorological data is no longer required to support the assessment process and consequently has not been undertaken. The current data used is collected using multiple deployments and over a longer period and thus provides a more realistic representation of site conditions than short deployments, thus allowing an assessment of the influence of meteorological conditions.*

## 3. Results and Discussion

A summary of the current data is shown in Figure 3 to Figure 11 and in Table 2 to Table 5. Over the period analysed for this report, the near-surface, middle and bottom cells had current speed averages of 6.52 cm/s, 5.82 cm/s and 5.06 cm/s respectively. This gave an overall average of 5.80 cm/s. The orientation of the tidal velocities was north-west – south-east.

Residual currents at the surface and mid-depth were toward the south (139°G and 280°G respectively, Figure 6 & Figure 7). The residual current for the near-bed cell was toward the south also (290°G, Figure 8). The magnitude of the residual currents for the surface, middle and bottom cells were moderate, with mean values of 0.051 m/s, 0.058 m/s and 0.065 m/s respectively.

## 4. Hydrographic Data Summary Sheets

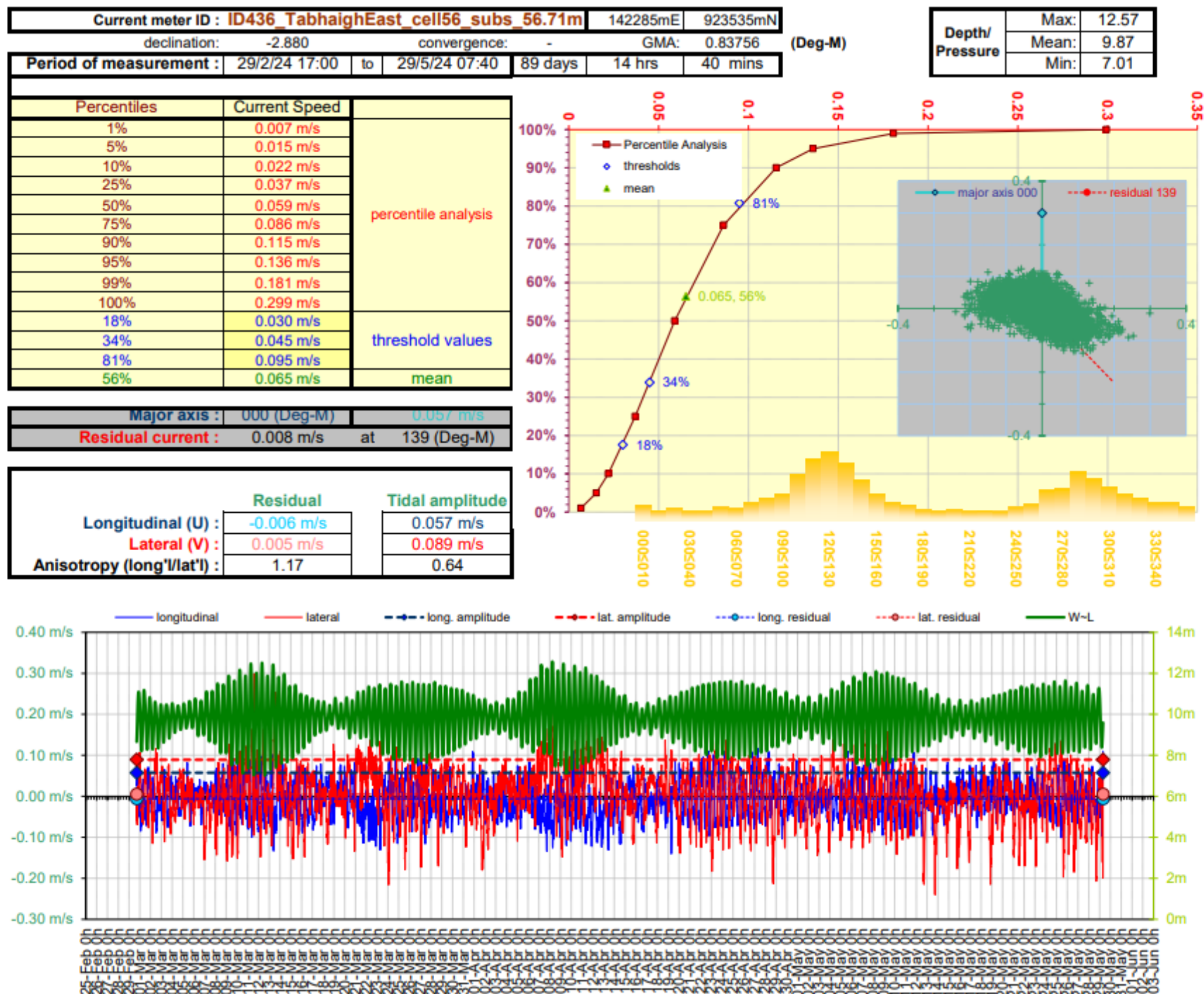


Figure 3. Current Data Summary Sheet for the surface current cell 54, 56.71 m from seabed, 29<sup>th</sup> February – 29<sup>th</sup> May 2024 inclusive (ID436).

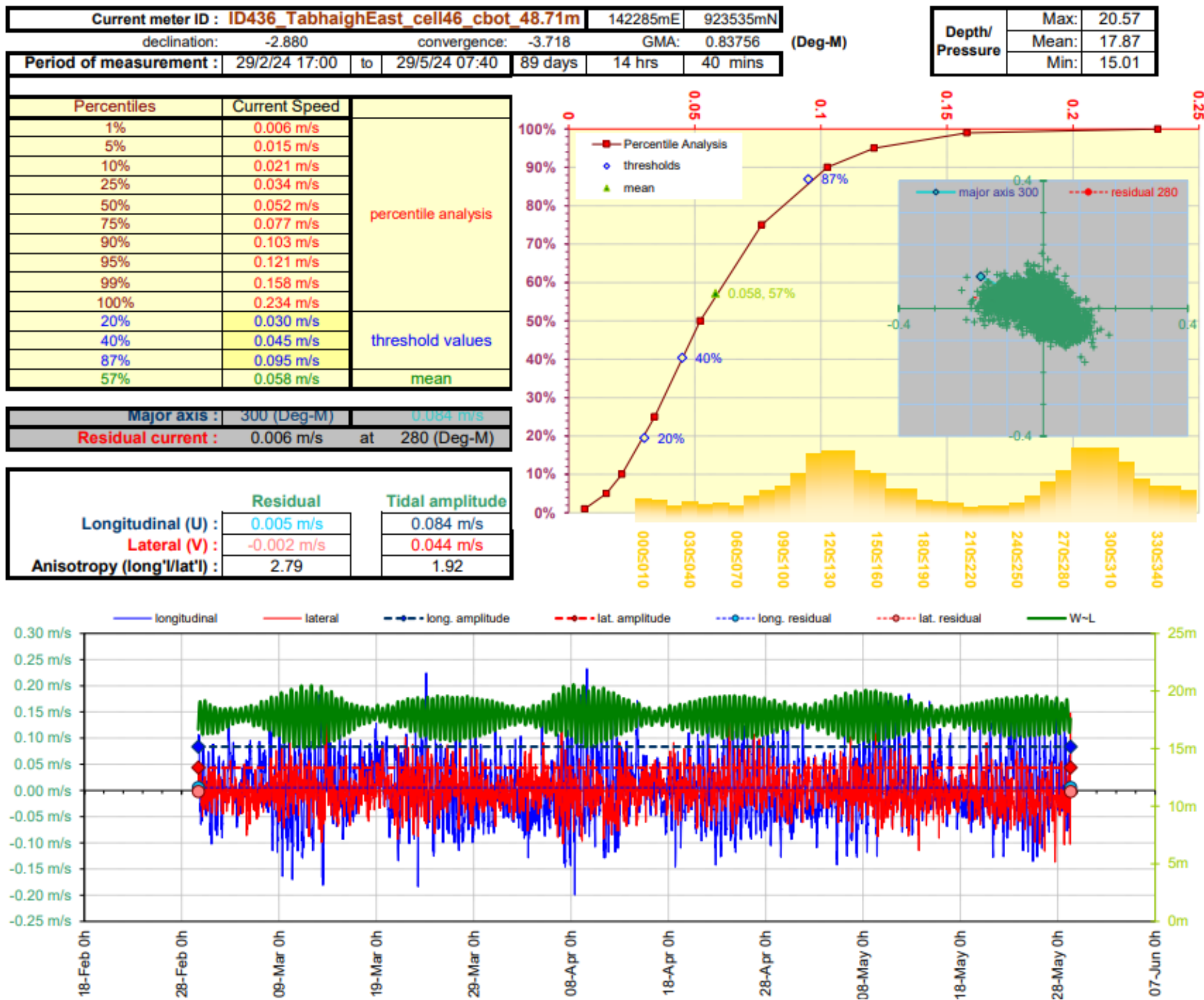


Figure 4. Current Data Summary Sheet for the cage bottom current cell 46, 48.71 m from seabed, 29<sup>th</sup> February – 29<sup>th</sup> May 2024 inclusive (ID436).

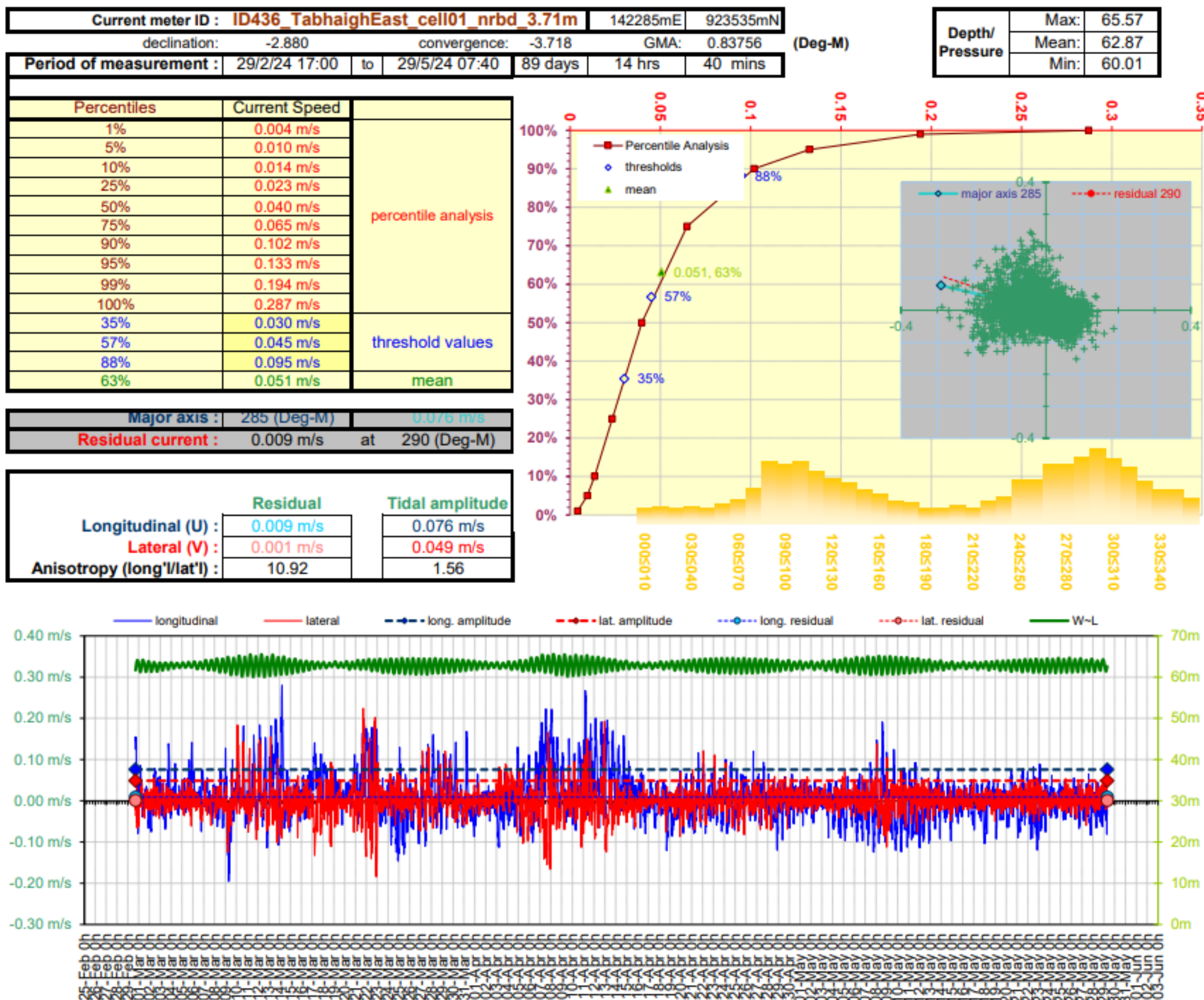


Figure 5. Current Data Summary Sheet for the near bottom current cell 1, 3.71m from seabed, 29<sup>th</sup> February – 29<sup>th</sup> May 2024 inclusive (ID436).

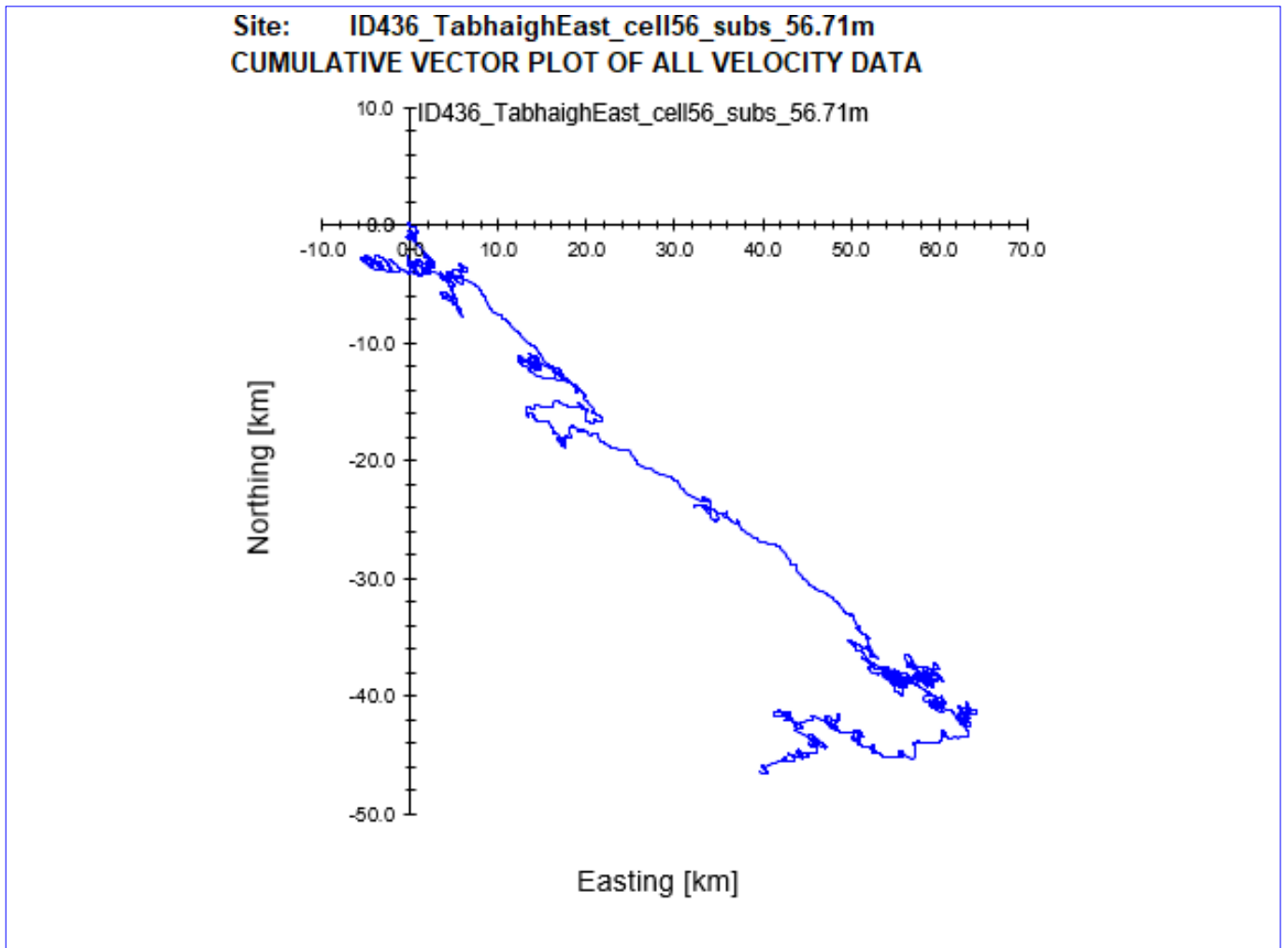


Figure 6. Cumulative Vector Plot of all velocity data from near surface cell for ID436.

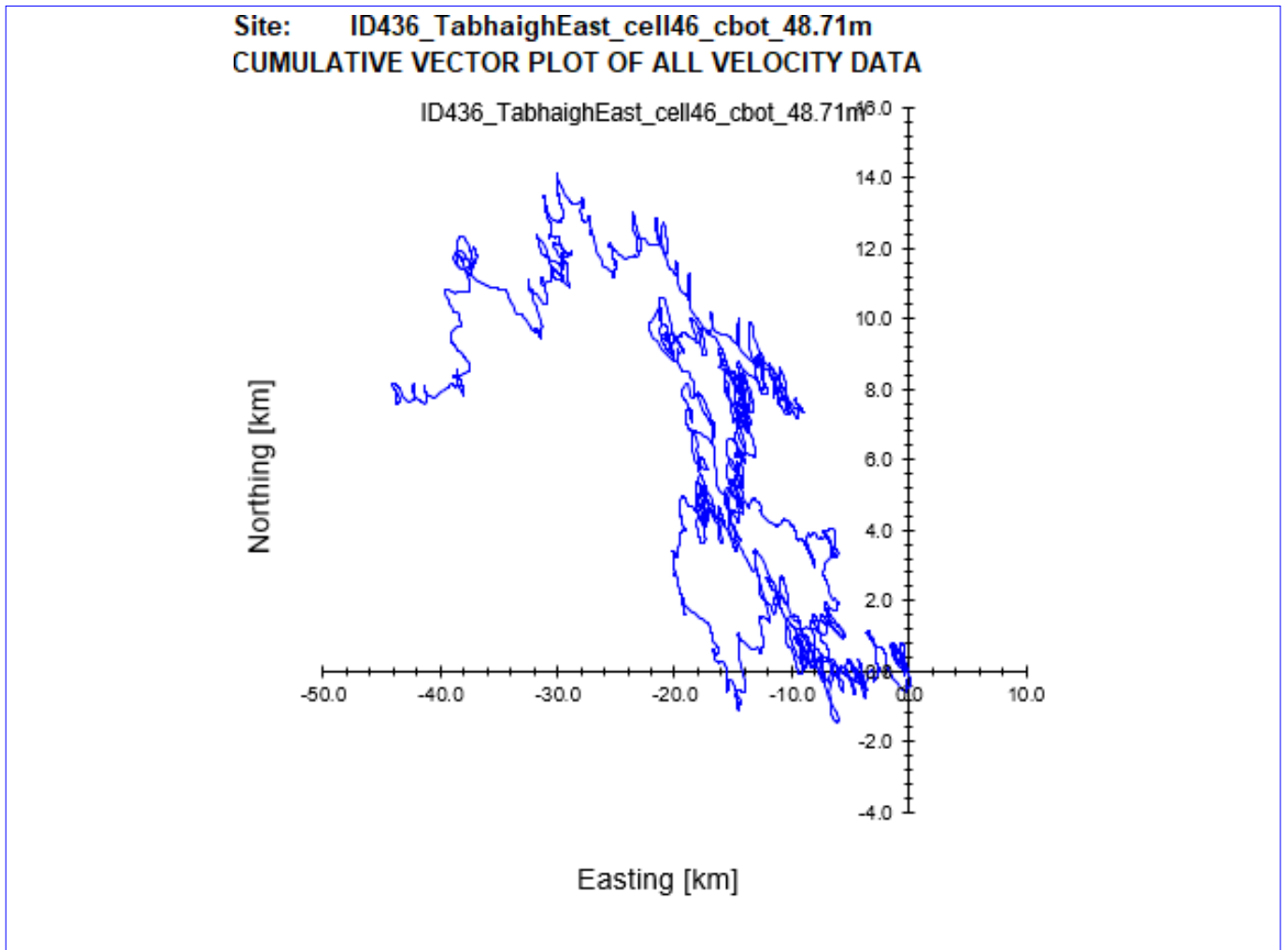


Figure 7. Cumulative Vector Plot of all velocity data from cage bottom cell for ID436.

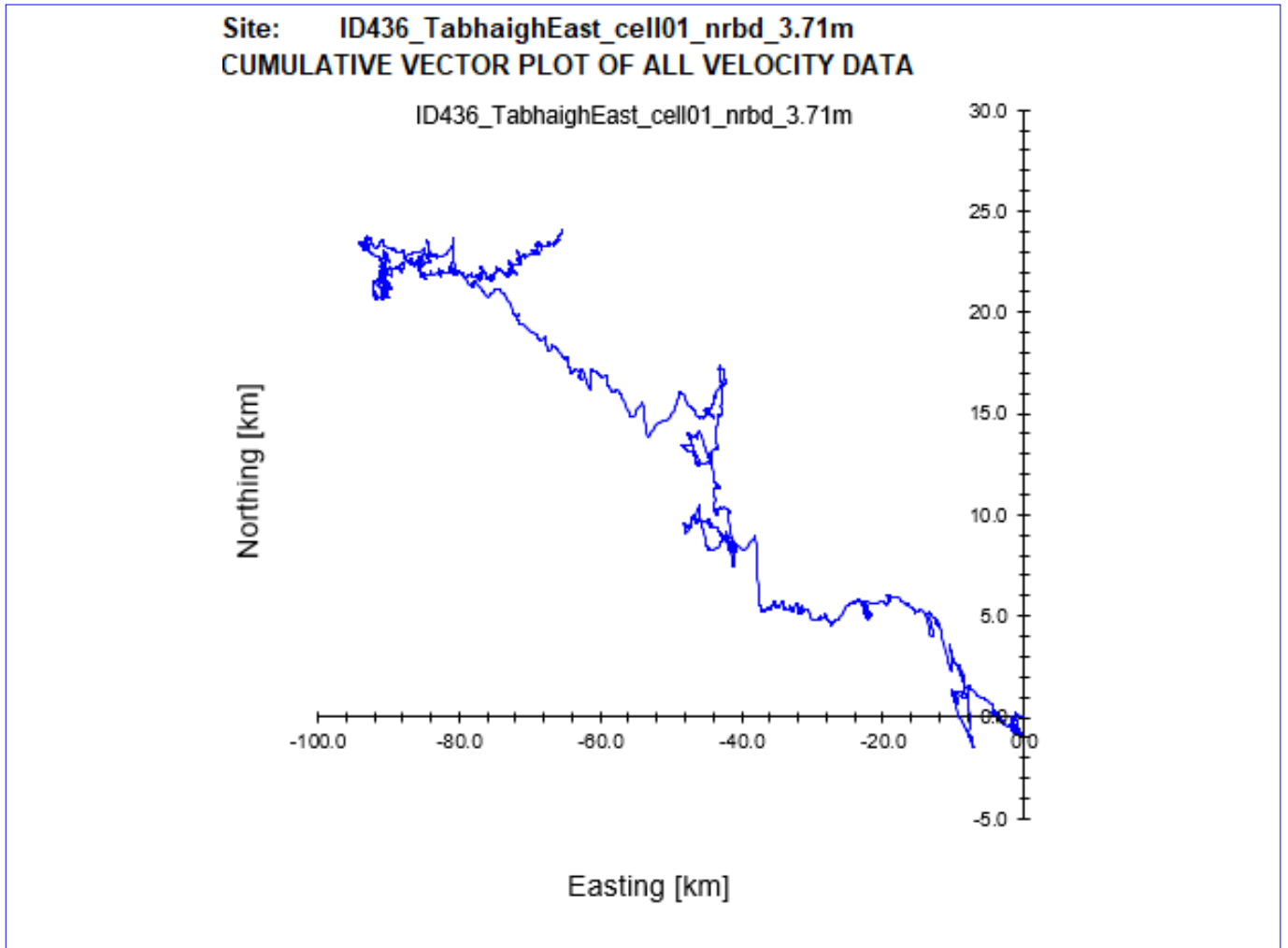


Figure 8. Cumulative Vector Plot of all velocity data from near bottom cell for ID436.

## 5. Summary of Current Data – ID436

Site Name: Tabhaigh East  
 Data start date: 29/02/2024  
 Data end date: 29/05/2024  
 Mean Water Depth: 66.58 m

Table 2. Summary of current meter deployment

	Cell	Depth Below Surface (m)	Distance from Seabed (m)	Mean current speed (cm/s)
Near surface:	54	7.01	56.71	6.52
Cage bottom:	46	15.01	48.71	5.82
Near bed:	1	60.01	3.71	5.06
Average current speed:				5.80

Table 3. Ranked percentiles for current speed at all three depths

Cell	Ranked Percentile (%) for mean speed	≤3cm/s (%)	≥4.5cm/s (%)	≥9.5cm/s (%)
Near surface:	56	18	66	9
Cage bottom:	57	20	60	13
Near bed:	63	35	43	12

Table 4. Major axis

Cell	Major Axis (Deg-G)
Near surface:	000
Cage Bottom:	300
Near bed:	285

Table 5. Mean and residual currents

Cell	Residual Speed (m/s)	Residual Parallel (m/s)	Residual Normal (m/s)	Tidal Amplitude Parallel (m/s)	Tidal Amplitude Normal (m/s)
Near Surface:	0.008	-0.006	0.005	0.057	0.089
Cage Bottom:	0.006	0.005	-0.002	0.084	0.044
Near Bed:	0.009	0.009	0.001	0.076	0.049

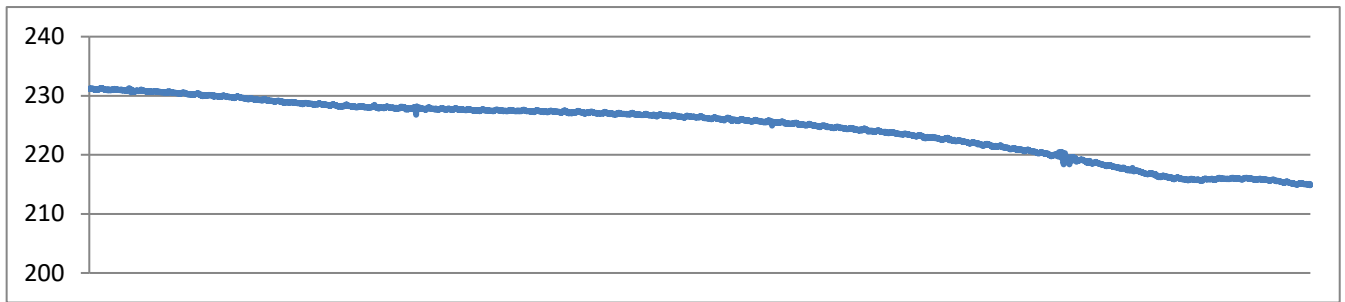


Figure 9. Summary of heading data from deployment ID436.

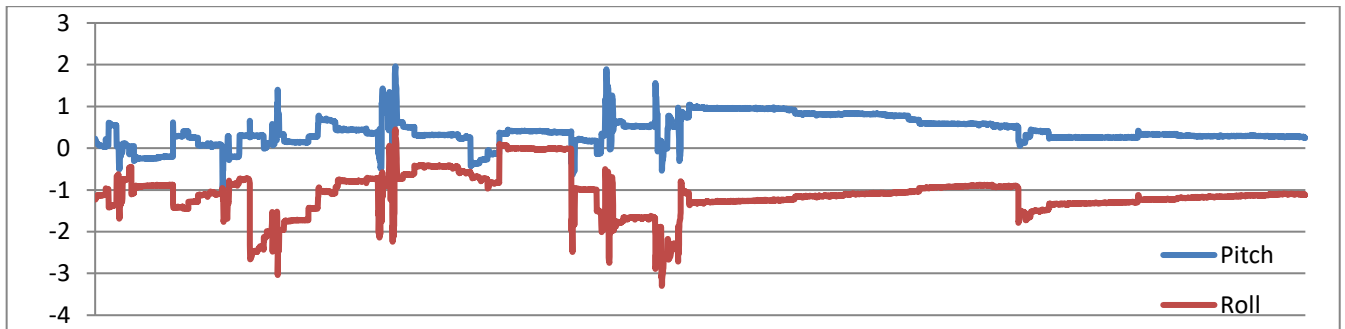


Figure 10. Summary of pitch and roll data from deployment ID436.

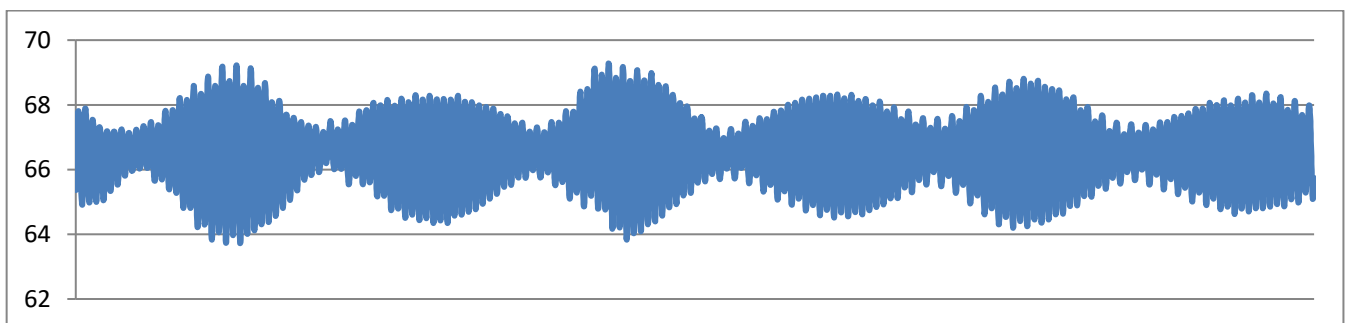


Figure 11. Pressure data from deployment ID436.

## 6. Conclusion

Mowi Scotland Ltd. has collected and analysed current and bathymetric data for the proposed new fish farm at Tabaigh East. The analysed current data for the 89 days and 14 hours period are believed to be reliable and representative of the proposed location. The bathymetric data from the wider-area UKHO bathymetry data supplemented with the local depth survey provided a coherent bathymetric dataset for the site.

## Annex 1. Survey Equipment Deployment Log

Location:	Tabhaigh East
Time zone:	UTC
Meter switched on:	17:00 29/02/2024
Meter switched off:	07:40 29/05/2024
Period used for this report:	17:00 29/02/2024 – 07:40 29/05/2024
ADCP serial number:	24616
Meter position:	58.12538N, -6.37873W 142285 E 923535 N
Minimum water depth:	63.72 m
Mean water depth:	66.58 m
Depth of meter from surface:	63.02 m (below minimum to transducer)
Height of meter from seabed:	0.7 m to transducer head
Sounding at deployment:	64 m @ 1605 on 29/02/2024

*Table A1. ADCP meter settings:*

Reference:	Transducer
Bin size (m):	1.0
Dist to 1 <sup>st</sup> bin (m):	3.01
Number of bins:	79
Frequency (kHz):	307
Recording interval (mins):	20
No. pings per ensemble:	300
Magnetic correction:	0
Ensemble:	300
Standard Deviation (cm/sec):	0.63
Time/Ping (seconds):	2