

# Tabhaigh, Loch Erisort Hydrographic Data Report: Deployment ID363 9th November 2020 to 3rd February 2021

February 2023 **Mowi Scotland Limited** 

> Registered in Scotland No. 138843 Registered Office, 1st Floor, Admiralty Park **Admiralty Road** Rosyth FIFE

**KY11 2YW** 

Farms Office, Glen Nevis Business Park PH33 6RX Fort William

Farms Office, Glen Nevis Business Park PH33 6RX Fort William

environment@mowi.com

http://mowi.com



### **CONTENTS**

1.	INTRODUCTION		
2.	MATERIALS & METHODS	5	
	2.1 Bathymetry2.2 Current Data	5 6	
	2.3 Magnetic Variation	6	
	2.4 Data Processing	7	
	2.5 Meteorological Data	10	
4.	HYDROGRAPHIC DATA SUMMARY SHEETS	11	
5.	SUMMARY OF CURRENT DATA – ID363	17	
6.	CONCLUSION	18	
AN	NEX 1. SURVEY EQUIPMENT DEPLOYMENT LOG	19	



## **LIST OF FIGURES**

Figure 1. Proposed and existing layouts at the Tabhaigh site. The current meter deployment	
locations are marked by the black triangles.	5
Figure 2. Bathymetry in the region around the proposed Tabhaigh salmon farm.	6
Figure 3. Mean intensity of the ADCP signal for the ID363 dataset plotted by bin number	9
Figure 4. Current Data Summary Sheet for the surface current cell 26, 28.72m from seabed, 9 <sup>th</sup>	
November to 3 <sup>rd</sup> February 2021 inclusive (ID363).	11
Figure 5. Current Data Summary Sheet for the cage bottom current cell 14, 16.72m from seabed	,
9 <sup>th</sup> November to 3 <sup>rd</sup> February 2021 inclusive (ID363).	12
Figure 6. Current Data Summary Sheet for the near bottom current cell 1, 3.7m from seabed, $9^{ ext{th}}$	
November to 3 <sup>rd</sup> February 2021 inclusive (ID363).	13
Figure 7. Cumulative Vector Plot of all velocity data from near surface cell for ID363.	14
Figure 8. Cumulative Vector Plot of all velocity data from cage bottom cell for ID363.	15
Figure 9. Cumulative Vector Plot of all velocity data from near bottom cell for ID363.	16
Figure 10. Summary of heading data from deployment ID363.	18
Figure 11. Summary of pitch and roll data from deployment ID363.	18
Figure 12. Pressure data from deployment ID363	18
LIST OF TABLES	
Table 1: Sentinel V100 ADCP Specifications.	8
Table 2. Summary of current meter deployment	17
Table 3. Ranked percentiles for current speed at all three depths	17
Table 4. Major axis	17
Table 5. Mean and residual currents	17



#### **QUALITY ASSURANCE**

Mowi Scotland Ltd is ISO9001 and ISO14001 accredited and all project management follows policies designed to ensure that the collection, collation and reporting of information produced in the course of our operations is done to a consistently high standard meeting the requirements of the end user.



#### 1. Introduction

Mowi Scotland Ltd. is preparing an application to the Scottish Environmental Protection Agency (SEPA) for an equipment change at the Tabhaigh salmon farm, located at the mouth of Loch Erisort, Isle of Lewis. Mowi Scotland Ltd. propose to change the site from  $10 \times 120 \text{m}$  pens to  $8 \times 160 \text{m}$  circumference pens, with 20 m deep nets on the pen string closest to Tabhaigh Beag and 15 m deep nets on the pen string furthest from Tabhaigh Beag, held in a 100 m grid.

Mowi Scotland Ltd have carried out hydrographic surveys at the site in 2020 and 2021. Hydrographic data at Stulaigh South was gathered during this time in two deployments:

- i. 9<sup>th</sup> November 2020 to 3<sup>rd</sup> February 2021 (ID363)
- ii. 10<sup>th</sup> February 2021 to 7<sup>th</sup> May 2021 (ID368)

This report describes the data from the 9<sup>th</sup> November 2020 to 3<sup>rd</sup> February 2021 deployment at Tabhaigh. The purpose of this report is to assess the suitability of the collected hydrographic data for calibration of a hydrodynamic model of the Loch Erisort region and input into the NewDepomod model.

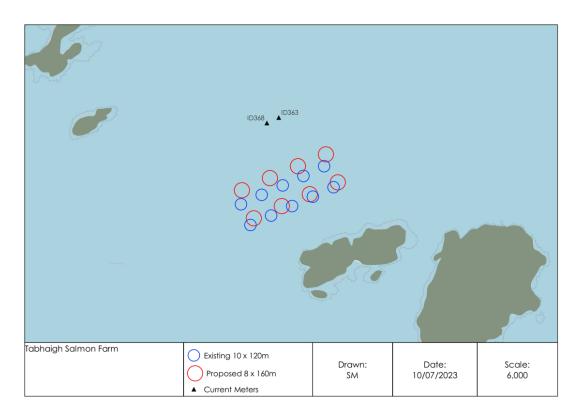


Figure 1. Proposed and existing layouts at the Tabhaigh site. The current meter deployment locations are marked by the black triangles.

#### 2. Materials & Methods

#### 2.1 Bathymetry

Bathymetry was taken from the ECLH model which has reasonably high spatial resolution around Loch Erisort (Figure 2).



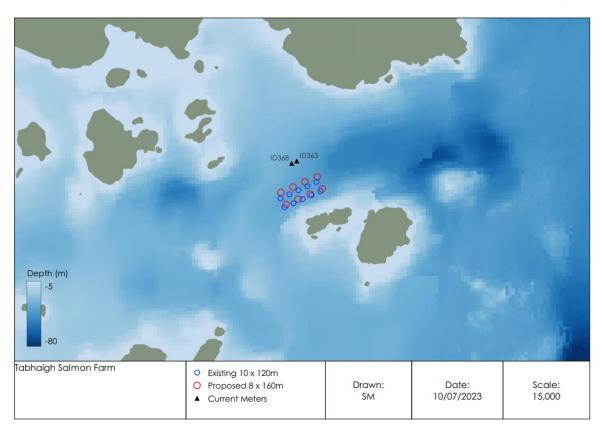


Figure 2. Bathymetry in the region around the proposed Tabhaigh salmon farm.

#### 2.2 Current Data

Mowi staff carried out hydrographic surveys at the site during 2018. The purpose of this hydrographic report is to assess the suitability of the collected hydrographic data for use with the NewDepomod and Hydrodynamic models. The data contained in this report were recorded at the site from 9<sup>th</sup> November 2020 to 3<sup>rd</sup> February 2021 (85 days and 12 hours of data; deployment ID363). The data from another deployment (ID368) are presented in a separate hydrographic report.

The Sentinel V100 (Wide) ADCP (Table 1), within its mooring frame, was positioned at 58.12352N, -6.39062W (141572E 923373N), which was approximately 440m from the nearest shoreline and approximately 240m from the centre of the proposed cage group (Figure 1). The transducer head was 70 cm from the base of the mooring frame. The mean depth (derived from the pressure sensor) at the Sentinel V100 ADCP position was 35.03 m.

Initial soundings were taken to establish the possible depth the Sentinel V100 ADCP would be situated at during high tide and so that the most appropriate cell size could be determined. The cell size was set at 1.0 m and the number of cells to 39.

Data was automatically written and stored to the internal memory within the Sentinel V100 ADCP main body and then downloaded to computer after completion of the deployment period via WiFi.

#### 2.3 Magnetic Variation

No magnetic variation correction was made to the Sentinel V100 ADCP during deployment, this was undertaken to the data after the instrument was recovered and data downloaded. The magnetic variation used was -3.5°; this was determined using the World Magnetic Model, produced jointly with the US National Oceanographic and Atmospheric Administration's National Geophysical Data center. Further details can be found at http://www.geomag.bgs.ac.uk/navigation.html



#### 2.4 Data Processing

Upon retrieval of the Sentinel V100 ADCP current meter, all data was downloaded to a computer for analysis. The raw data file was opened in Teledyne's "Velocity" software and Matlab. Deployment diagnostic data (beam intensity, correlation, pitch and roll) were analysed to confirm that the deployment was successful with the instrument orientated upright. The heading data were also examined to identify any movement of the Sentinel V100 ADCP mooring frame during the deployment.

The diagnostic data suggested that velocities from the first 26 bins were valid (Figure 3). Calculations were undertaken to identify the cells to be used for surface and middle currents. Surface data was taken at an average depth (derived from the pressure sensor) of 6.31 m (cell 26), and cage-bottom data at 18.31 m (cell 14). Surface and middle cell heights were 28.72 m and 16.72 m from the seabed respectively. The bottom cell (cell 1) was at an average depth of 31.31 m and 3.72 m above the seabed.



Table 1: Sentinel V100 ADCP Specifications.

2.0m	Depth Cell Size <sup>1</sup>	V20 (1000kHz)		V50 (500kHz)		V100 (	(300kHz)	
0.3m   19-3/24.0   11.1/20.8     0.5m   20.2/24.9   7.1/13.4   44.1/57.6   19.2/36.5     1.0m   22.1/26.9   3.6/6.7   50.5/64.6   7.1/13.5   94.5/120.6   10.9/26.5     2.0m   24.5/29.4   17/3.2   56.0/70.6   3.6/6.7   103.5/130.4   52.7/5.6.0     4.0m   26.9/32.0   0.8/1.6   63.1/78.2   17/5.2   114.6/14.2   5.7/10.6     6.0m   6.9/32.0   0.8/1.6   63.1/78.2   17/5.2   114.6/14.2   5.7/5.6.0     6.0m   6.9/32.0   0.8/1.6   63.1/78.2   17/5.2   114.6/14.2   5.7/5.6.0     6.0m   6.9/32.0   0.8/1.6   63.1/78.2   17/2.1   121.7/151.5   18/3.5     6.0m   6.9/32.0   0.8/1.6   63.1/78.2   17/2.1   121.7/151.5   18/3.5     6.0m   6.9/32.0   0.8/1.6   63.1/78.2   17/2.2   114.6/14.2   5.7/5.5     7.0m   7.0		Depth Cell Size <sup>1</sup>						
0.3m   19.3/24.0   11.1/20.8     0.5m   20.2/24.9   71.1/3.1   4.41.57.6   19.2/36.5     1.0m   22.1/26.9   3.6/6.7   50.3/64.6   71.1/13.5   94.5/120.6   10.9/20.6     2.0m   24.3/29.4   17/3.2   56.0/70.6   3.6/6.7   10.3/31.30.4   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04   5.3/13.04		0.25m	18.0/22.6	19.2/36.5				
0.5m   20.2/4.99   7.1/13.4   44.1/57.6   19.2/36.5     1.0m   22.1/26.9   3.6/6.7   50.5/64.6   7.1/13.5   94.5/120.6   10.9/20     2.10m   24.5/7.94   1.7/5.2   56.0/70.6   3.6/6.7   103.5/130.4   5.5/10.6     2.10m   24.5/7.94   1.7/5.2   56.0/70.6   3.6/6.7   103.5/130.4   5.5/10.6     4.0m   26.9/32.0   0.8/1.6   63.1/7.82   1.7/3.2   114.6/142.3   2.7/5.     6.0m   6.0m   6.0m   6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m   6.0m   6.0m     6.0m   6.0m   6.0m		0.3m						
1.0m   22.1/26.9   3.6/6.7   50.5/44.6   7.1/13.5   94.5/120.6   10.9/2C     2.0m   24.5/29.4   1.7/3.2   56.0/70.6   3.6/6.7   10.35/130.4   5.5/10     4.0m   26.9/32.0   0.8/1.6   63.1/78.2   1.7/3.2   114.6/142.3   2.7/5.5     6.0m   6.60m   6.69/32.0   0.8/1.6   63.1/78.2   1.7/3.2   114.6/142.3   2.7/5.5     6.0m   6.60m   6.		0.5m			44.1/57.6	19.2/36.5		
2.0m		1.0m					94.5/120.6	10.9/20.6
4.0m 26.9/32.0 0.8/1.6 63.1/18.2 1.7/5.2 114.6/142.3 2.7/5. 6.0m Vireless   So2.11b/g/n   One 16.68 Micro SD Card included    Profile Parameters   Velocity accuracy   V20,V50: 0.3% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5% of the water velocity relative to the ADCP ±0.5cm/s V100: 0.5 m/s (featurity) ±2.0m/s (featuri		2.0m			•			
Internal memory  One 16GB Micro SD Card included  Profile Parameters  Velocity accuracy  Velocity accuracy  Velocity resolution Velocity range Ping rate  Echo Intensity Profile  Vertical resolution Dynamic range Precision  Transducer and Hardware  Beam angle Configuration Depth rating Materials  Transducer, housing, and end cap: plastic Connector: metal shell  Standard Sensors  Temperature (mounted on transducer) Till (MEMS accelerometers) Pressure sensor (mounted on transducer) Pressure sensor (mounted on transducer) Pressure sensor (mounted on transducer) Battery pack @5*C Storage temperature Welpfit in air Velocity and Velocity and Velocity and Velocity and Velocity and Velocity resolution Velocity #20m/s (maximum) Velocity #20m/s for the water velocity #20m/s fored water velocity #20m/s for the water velocity #20m/s for the wa						1.7/3.2	114.6/142.3	2.7/5.2
Velocity resolution Velocity range Ping rate  Vertical resolution Dynamic range Precision  Transducer and Hardware  Beam angle Configuration Depth rating Materials  Standard Sensors  Temperature (mounted on transducer) Compass (magnetio-inductive sensor) Tilt (MEMS accelerometers) Tilt (MEMS accelerometers) Pressure sensor (mounted on transducer) Pressure sensor (mounted on transducer) Range 300m, accuracy 0.1%FS  Power  External DC input Internal battery voltage Battery capacity; over-the-counter @0°C Battery pack @5°C  Software  Velocity resolution D.1°C Vertical resolution Depth rating Depth cell size B808  25° 25° 26 beam, convex; 5th beam vertical Depth rating 200m Transducer, housing, and end cap: plastic Connector: metal shell Connector: metal shell Range -5° to 45°C, precision ±0.4°C, resolution 0.1° Accuracy 2° RMS, resolution 0.1° Accuracy 2° RMS, resolution 0.1° Accuracy 2° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  Power  External DC input Internal batteryvoltage Battery capacity; over-the-counter @0°C Battery pack @5°C  Software  Teledyne RDI's new software included  ReadyV—Pre-deployment (testing, planning, and data recovery) 5 Velocity—Post-processing (data handling, display, and export) 6  Environmental  Standard depth rating Operating temperature Storage temperature (without batteries) Weight in water  Weight in water  Weight in water  External battery case	Communications and Recording					ard included		
Velocity resolution Velocity range Ping rate  Vertical resolution Dynamic range Precision  Transducer and Hardware  Beam angle Configuration Depth rating Materials  Transducer and Hardware  Standard Sensors  Temperature (mounted on transducer) Compass (magneto-inductive sensor) Tilt (MEMS accelerometers) Pressure sensor (mounted on transducer) Precision 0.05° RMS, resolution 0.1°, max. dip angle 85° Pitch range ±90°, roll range ±180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  Pressure sensor (mounted on transducer) Precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  12-20VDC 18VDC new Battery capacity, over-the-counter (@0°C Battery pack @5°C  18VDC new Battery capacity, over-the-counter (@0°C Battery pack @5°C  100 wat hours (typical) Software  Teledyne RDI's new software included  ReadyV—Pre-deployment (testing, planning, and data recovery) 5 Velocity—Post-processing (data handling, display, and export) 6  Environmental  Standard depth rating Operating temperature Software  Velocity—Post-processing (data handling, display, and export) 6  Environmental  Velight in air Velight in water  No 45°C  100 Water 100 Felont 100 Felont 100 Fe	Profile Parameters	Velocity accuracy						
Velocity range Ping rate Up to 4Hz  Echo Intensity Profile Vertical resolution Dynamic range 80dB Precision ±1.5dB  Transducer and Hardware Beam angle Configuration Depth rating 200m Harrials Transducer, housing, and end cap: plastic Connector: metal shell  Standard Sensors Temperature (mounted on transducer) Range +5° to 45°C, precision ±0.4°C, resolution 0.1° Accuracy 2° RMS, resolution 0.1°, max. dip angle 85° Pitch range ±90°, roll range ±80°, accuracy 2° RMS, precision ±0.5° RMS, resolution 0.1° Range +90°, roll range ±80°, accuracy 2° RMS, precision ±0.5° RMS, resolution 0.1° Range 300m, accuracy 2° RMS, precision ±0.5° RMS, resolution 0.1° Range ±80°, accuracy 2° RMS, precision ±0.5° RMS, resolution 0.1° Range ±80°, accuracy 2° RMS, precision ±0.5° RMS, resolution 0.1° Range ±80°, accuracy 2° RMS, precision ±0.5° RMS, resolution 0.1° Range ±80°, accuracy 2° RMS, precision ±0.5° RMS, resolution 0.1° Range ±80°, accuracy 2° RMS, precision ±0.5° RMS, resolution 0.1° Range ±80°, accuracy 2° RMS, precision		Valority resolution				21 Velocity relative to	J the Aucr ±0.5cm	1/2
Ping rate  Vertical resolution Dynamic range Precision  Transducer and Hardware  Beam angle Configuration Depth rating Materials  Temperature (mounted on transducer) Compass (magneto-inductive sensor) Tilt (MEMS accelerometers) Pressure sensor (mounted on transducer) Pressure sensor (mounted on transducer) Pressure years of (mounted on transducer) Pressure years of (mounted on transducer) Battery capacity; over-the-counter (@0°C Battery pack @5°C Battery pack @5°C  Environmental  Vertical resolution Depth retl size Sodware  Poeth cell size Sodware  Depth cell size Sodware  Sodware  Sodware  Sodware  Standard depth rating Operating temperature Storage temperature (without batteries) Weight in sir Weight in water  Sodware  Sodware  Standard battery case		•				/c /mavimum)		
Dynamic range Precision #1.5dB  Transducer and Hardware Beam angle Configuration Depth rating Materials Transducer, housing, and end cap: plastic Connector: metal shell  Standard Sensors Temperature (mounted on transducer) Compass (magneto-inductive sensor) Accuracy 2° RMS, cesolution 0.1° Accuracy 2° RMS, cesolution 0.1° Pitch range #90°, roll range #180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Pitch range #90°, roll range #180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  Power External DC input 12-20VDC 18VDC external DC input 18VDC new Battery capacity; over-the-counter @0°C Battery pack @5°C 1510 watt hours (typical) S10 watt hours  Software Teledyne RDI's new software included ReadyW-Pre-deployment (testing, planning, and data recovery) Velocity-Post-processing (data handling, display, and export)						5 (Maximum)		
Precision #1.5dB  Transducer and Hardware Beam angle Configuration Depth rating Aterials Transducer, housing, and end cap: plastic Connector: metal shell  Standard Sensors Temperature (mounted on transducer) Accuracy 2° RMS, precision #0.4°C, resolution 0.1° Accuracy 2° RMS, precision #0.4°C, resolution 0.1° Accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range #180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  Power External DC Input Internal battery voltage Battery capacity; over-the-counter @0°C Battery pack @5°C #100 watt hours  Software Teledyne RDI's new software included ReadyW-Pre-deployment (testing, planning, and data recovery) Velocity —Post-processing (data handling, display, and export) Post-processing (dat	Echo Intensity Profile	Vertical resolution			Depth cell size			
Transducer and Hardware  Beam angle Configuration Depth rating Materials  Temperature (mounted on transducer) Compass (magneto-inductive sensor) Tilt (MEMS accelerometers) Pressure sensor (mounted on transducer) Internal battery voltage Battery pack @5°C Battery pack @5°C Battery pack @5°C  Teledyne RDI's new software included  Standard depth rating Operating temperature Storage temperature Storage temperature Weight in air Weight in water  External battery case  Beam angle 25° 4-beam, convex; 5th beam vertical 200m Transducer, housing, and end cap: plastic Connector: metal shell  Range -5° to 45°C, precision ±0.4°C, resolution 0.1° Accuracy 2° RMS, resolution 0.1°, max. dip angle 85° Pitch range ±90°, roll range ±180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  12-20VDC 18VDC new 100 watt hours (typical) 510 watt hours 100 watt hours Velocity—Post-processing (data handling, display, and export) 5° Velocity—Post-processing (data handling, display, and export) 6° Environmental  Standard depth rating Operating temperature Storage temperature (without batteries) Weight in air Weight in water  External battery case		Dynamic range						
Configuration Depth rating Materials  Transducer, housing, and end cap: plastic Connector: metal shell  Standard Sensors  Temperature (mounted on transducer) Compass (magneto-inductive sensor) Tilt (MEMS accelerometers) Pitch range ±90°, roll range ±180°, accuracy 2° RMS, precision 0.1° Range 300m, accuracy 0.1%FS  Power External DC input Internal battery voltage Battery capacity; over-the-counter @0°C Battery pack @5°C Software Teledyne RDI's new software included ReadyV—Pre-deployment (testing, planning, and data recovery) 5 Velocity—Post-processing (data handling, display, and export) 6  Environmental Standard depth rating Operating temperature Storage temperature (without batteries) Weight in air Weight in water  Available Options  External battery case		Precision			±1.5dB			
Depth rating Materials  Temperature (mounted on transducer) Compass (magneto-inductive sensor) Tilt (MEMS accelerometers) Pressure sensor (mounted on transducer) Internal battery voltage Battery capacity; over-the-counter @0°C Battery pack @5°C  Teledyne RDI's new software included  Teledyne RDI's new software included  Standard depth rating Operating temperature Storage temperature (without batteries) Weight in air Weight in water  Description 0.05° to 45°C, precision ±0.4°C, resolution 0.1° Accuracy 2° RMS, resolution 0.1° max. dip angle 85° Pitch range ±90°, roll range ±180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  12-20VDC 18VDC new 18VDC new 100 watt hours (typical) 510 watt hours  Software  Teledyne RDI's new software included ReadyW-Pre-deployment (testing, planning, and data recovery) 5 Velocity -Post-processing (data handling, display, and export) 6  Environmental Standard depth rating Operating temperature -5° to 45°C Storage temperature (without batteries) Weight in air 7.5kg - 16.0kg Weight in water  Available Options External battery case	Transducer and Hardware	_						
Materials  Transducer, housing, and end cap: plastic Connector: metal shell  Standard Sensors  Temperature (mounted on transducer) Compass (magneto-inductive sensor) Tilt (MEMS accelerometers) Pressure sensor (mounted on transducer) Pressure sensor (mounted on transducer) Pressure sensor (mounted on transducer)  External DC input Internal battery voltage Battery capacity; over-the-counter @0°C Battery pack @5°C Battery pack @5°C  Teledyne RDI's new software included  Standard depth rating Operating temperature Storage temperature (without batteries) Weight in air Weight in water  Available Options  Texternal battery case  Transducer, housing, and end cap: plastic Connector: metal shell  Range -5° to 45°C, precision ±0.4°C, resolution 0.1° Accuracy 2° RMS, resolution 0.1°, max. dip angle 85° Pitch range ±90°, rolt range ±180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  12-20VDC 112-20VDC 118VDC new 100 watt hours (typical) 100 watt hours  Velocity—Post-processing (data handling, and data recovery) 5 Velocity—Post-processing (data handling, display, and export) 6  Environmental  Standard depth rating Operating temperature -5° to 45°C -5° to 45°C -50° to 60°C						eam vertical		
Connector: metal shell  Standard Sensors  Temperature (mounted on transducer) Compass (magneto-inductive sensor) Tilt (MEMS accelerometers) Pressure sensor (mounted on transducer) Pressure sensor (mounted on transducer)  External DC input Internal battery voltage Battery capacity; over-the-counter @0°C Battery pack @5°C  Teledyne RDI's new software included  Teledyne RDI's new software included  Standard depth rating Operating temperature Storage temperature (without batteries) Weight in air Weight in water  External battery case  Connector: metal shell  Range -5° to 45°C, precision ±0.4°C, resolution 0.1° Accuracy 2° RMS, resolution 0.1°, max. dip angle 85° Pitch range ±90°, roll range ±180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  12-20VDC 18VDC new 18VDC new 100 watt hours (typical) 510 watt hours  ReadyW-Pre-deployment (testing, planning, and data recovery) 5 Velocity-Post-processing (data handling, display, and export) 6  Environmental  Standard depth rating Operating temperature -5° to 45°C -30° to 60°C 7.5kg - 16.0kg Weight in air Weight in water  External battery case								
Compass (magneto-inductive sensor) Tilt (MEMS accelerometers) Pitch range ±90°, roll range ±180°, accuracy 2° RMS, precision 0.1°, max. dip angle 85° Pitch range ±90°, roll range ±180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  Power  External DC input Internal battery voltage Battery capacity; over-the-counter @0°C Battery pack @5°C  Teledyne RDI's new software included  ReadyV—Pre-deployment (testing, planning, and data recovery) 5 Velocity—Post-processing (data handling, display, and export) 6  Environmental  Standard depth rating Operating temperature Storage temperature (without batteries) Weight in air Weight in water  Available Options  External battery case		Materials						
Tilt (MEMS accelerometers) Pitch range ±90°, roll range ±180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  Power External DC input	Standard Sensors	Temperature (mounter	d on transducer)		Range -5° to 45°C, pre	cision ±0.4°C, resolu	ition 0.1°	
Tilt (MEMS accelerometers) Pitch range ±90°, roll range ±180°, accuracy 2° RMS, precision 0.05° RMS, resolution 0.1° Range 300m, accuracy 0.1%FS  Power External DC input								
Pressure sensor (mounted on transducer)  Range 300m, accuracy 0.1%FS  External DC input Internal battery voltage Battery capacity; over-the-counter @0°C Battery pack @5°C  Software  Teledyne RDI's new software included  ReadyV—Pre-deployment (testing, planning, and data recovery) 5 Velocity—Post-processing (data handling, display, and export) 6  Environmental  Standard depth rating Operating temperature Storage temperature (without batteries) Weight in air Weight in water  Available Options  External battery case		Tilt (MEMS accelerome	ters)		Pitch range ±90°, roll ra	range ±180°, accurac		
Power  External DC input Internal battery voltage Battery capacity; over-the-counter @0°C Battery pack @5°C 100 watt hours  Software  Teledyne RDI's new software included  ReadyV—Pre-deployment (testing, planning, and data recovery) Velocity—Post-processing (data handling, display, and export) Velocity—Post-processing (data handling, display, data handling, display, and export) Velocity—Post-processing (data handling, display, dat					precision 0.05° RMS, re	solution 0.1°		
Internal battery voltage Battery capacity; over-the-counter @0°C Battery pack @5°C  Software  Teledyne RDI's new software included  ReadyV—Pre-deployment (testing, planning, and data recovery) 5 Velocity—Post-processing (data handling, display, and export) 6  Environmental  Standard depth rating Operating temperature Storage temperature (without batteries) Weight in air Weight in water  Available Options  External battery case		Pressure sensor (mou	inted on transdu					
Battery capacity; over-the-counter @0°C Battery pack @5°C  Software  Teledyne RDI's new software included  ReadyV—Pre-deployment (testing, planning, and data recovery) 5 Velocity—Post-processing (data handling, display, and export) 6  Environmental  Standard depth rating Operating temperature Storage temperature (without batteries) Weight in air Weight in water  Available Options  External battery case	Power							
Battery pack @5°C  510 watt hours  Feledyne RDI's new software included  ReadyW—Pre-deployment (testing, planning, and data recovery)  Velocity—Post-processing (data handling, display, and export)  Environmental  Standard depth rating Operating temperature Storage temperature (without batteries) Veight in air Weight in water  Available Options  External battery case								
Software  Teledyne RDI's new software included  ReadyW—Pre-deployment (testing, planning, and data recovery)  Velocity—Post-processing (data handling, display, and export)  Environmental  Standard depth rating Operating temperature Storage temperature (without batteries) Veight in air Weight in water  Available Options  ReadyW—Pre-deployment (testing, planning, and data recovery)  Sometimes of the storage of			r-the-counter @	•		l)		
Velocity – Post-processing (data handling, display, and export) 6  Environmental Standard depth rating 200m Operating temperature -5° to 45°C Storage temperature (without batteries) -30° to 60°C Weight in air 7.5kg – 16.0kg Weight in water 1.6kg – 6.0kg  Available Options External battery case		Battery pack @5°C			510 watt hours			
Operating temperature Storage temperature (without batteries) Weight in air Weight in water  Available Options  Operating temperature (without batteries) -30° to 60°C 7.5kg – 16.0kg 1.6kg – 6.0kg  External battery case	Software	Teledyne RDI's new software included						
Storage temperature (without batteries) Weight in air Weight in water  Available Options  Storage temperature (without batteries) 7.5kg – 16.0kg Weight in water 1.6kg – 6.0kg	Environmental							
Weight in air 7.5kg – 16.0kg Weight in water 1.6kg – 6.0kg  Available Options External battery case		Operating temperatu	re					
Weight in water 1.6kg - 6.0kg  Available Options External battery case			(without batteries	•				
Available Options External battery case								
		Weight in water	ater 1.6kg – 6.0kg					
WWW.\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	Available Options							
Dimensions Special configuration drawing available upon request	Dimensions							

- 2. Nanges special are typical at inspeciative 50 °C and sample of 53
  3. User selects the bandwidth mode; wide ~ 25% or narrow ~ 6%.
  4. Standard deviations (Srd Dev) are typical values for single ping data
  5. Resident in ADCP accessed via a web browses.
  6. Windows M based software program.



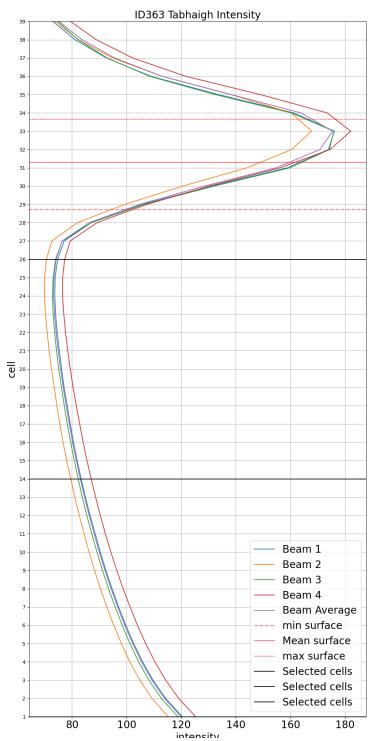


Figure 3. Mean intensity of the ADCP signal for the ID363 dataset plotted by bin number.

The 'first cell range' is automatically calculated by the instrument, which is the distance from the transducer head to the first cell. For this deployment, the first cell range was calculated as 3.02 m. This value is then added to the height of the instrument frame (0.7 m) to get the first cell height above the seabed, which equated to 3.72 m

Standard deviation has been assessed throughout the deployment to identify accurate and reliable data for near bed, middle (net depth) and surface cells using the following equation:

$$Cell \, StdDev = \frac{Instrument \, StdDev}{\sqrt{No. \, valid \, pings}} \tag{1}$$



The Instrument Standard Deviation (StdDev) in Equation 1 is determined using the deployment settings when the meter is programmed, examples of the StdDev values for different configurations are shown in Table 1. This deployment had a cell size of 1m which equates to an Instrument StdDev of 10.9 cm/s.

The Percentage of valid pings used to calculate Cell StdDev is derived using "Percentage Good" data which allows us to relate the StdDev to the actual data gathered. The percent good data is available for 1, 2, 3 and 4 beams which represent the following:

- Percent good 1 = % of good data computed from 3 Beams
- Percent good 2 = % of bad data due to more than 2 Beam bad
- Percent good 3 = % of bad data due to error velocity exceeded
- Percent good 4 = % of good data computed from 4 Beams

The method described has been used to calculate the Standard deviation throughout the deployment for the surface, middle and bottom cells; the average StdDev values for the surface, middle and bottom was 0.63cm/s, 0.63cm/s and 0.63cm/s respectively which are all within the SEPA criteria of 2cm/s.

#### 2.5 Meteorological Data

The collection of meteorological data is no longer required to support the assessment process and consequently has not been undertaken. The current data used is collected using mulitple deployments and over a longer period and thus provides a more realistic representation of site conditions than short deployments, thus allowing an assessment of the influence of meterological conditions.

#### 3. Results and Discussion

A summary of the current data is shown in Figure 4 to Figure 12 and in Table 2 to Table 5. Over the period analysed for this report, the near-surface, middle and bottom cells had current speed averages of 6.26 cm/s, 6.49 cm/s and 6.21 cm/s respectively. This gave an overall average of 6.32 cm/s. The orientation of the tidal velocities was north-east – south-west.

Residual currents at the surface (53°G, Figure 7) were toward the north-east while the mid-depth (286°G, Figure 8) were towards the north-west and near-bottom cells were toward the south-west (244°G, Figure 9). The magnitude of the residual currents for the surface, middle and bottom cells were moderate, with mean values of 0.013 m/s, 0.019 m/s and 0.024 m/s respectively.



### 4. Hydrographic Data Summary Sheets

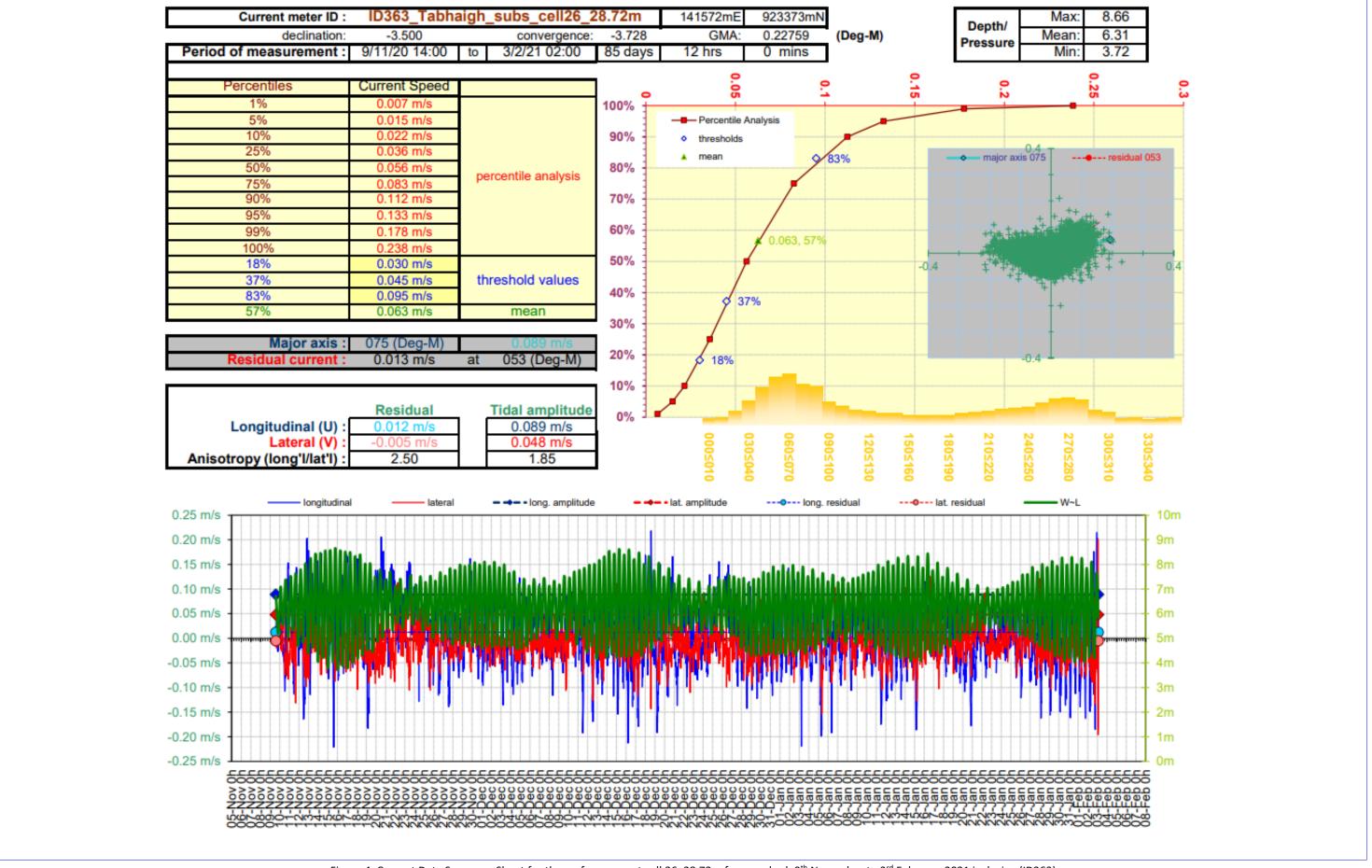


Figure 4. Current Data Summary Sheet for the surface current cell 26, 28.72m from seabed, 9<sup>th</sup> November to 3<sup>rd</sup> February 2021 inclusive (ID363).



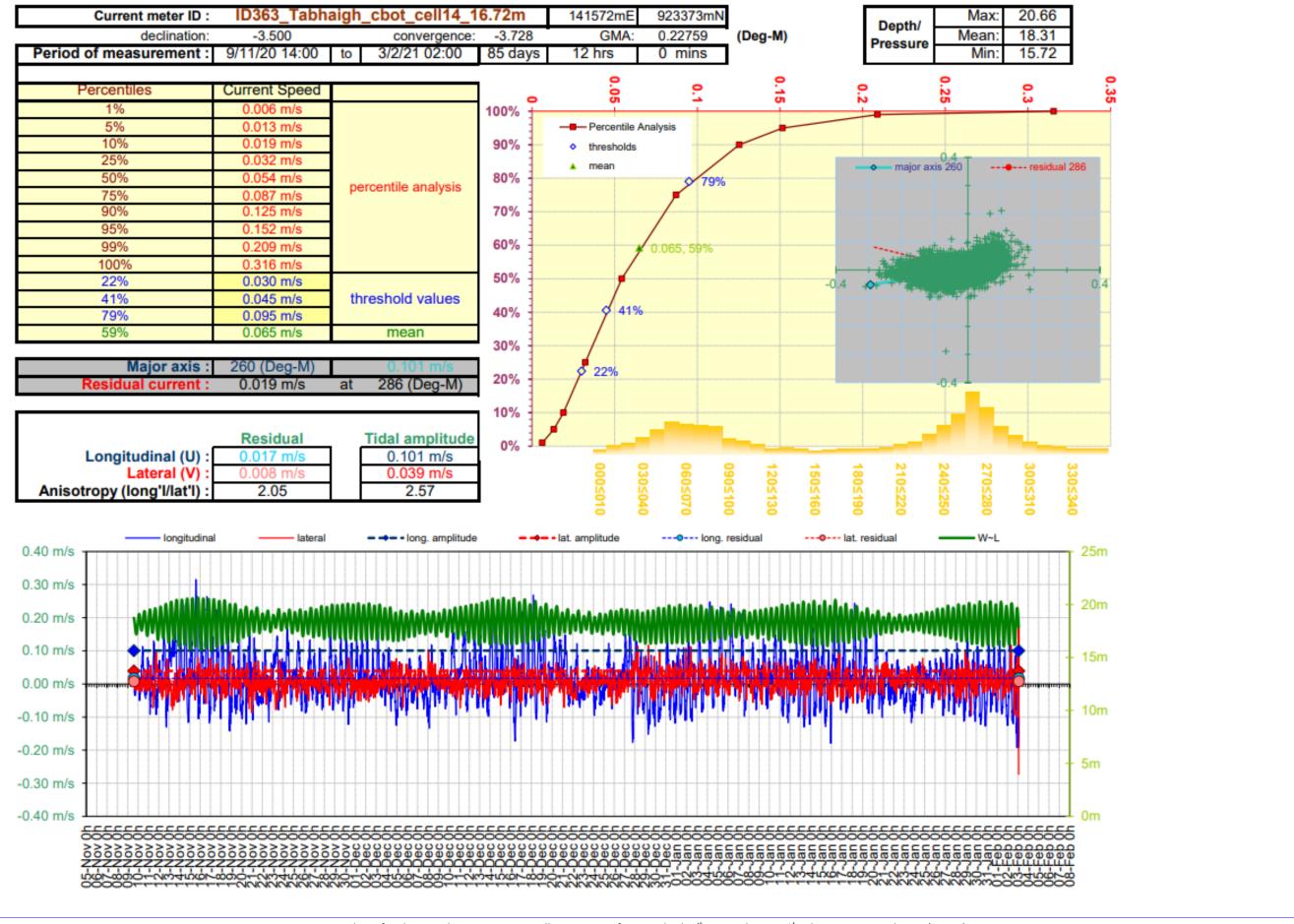


Figure 5. Current Data Summary Sheet for the cage bottom current cell 14, 16.72m from seabed, 9<sup>th</sup> November to 3<sup>rd</sup> February 2021 inclusive (ID363).



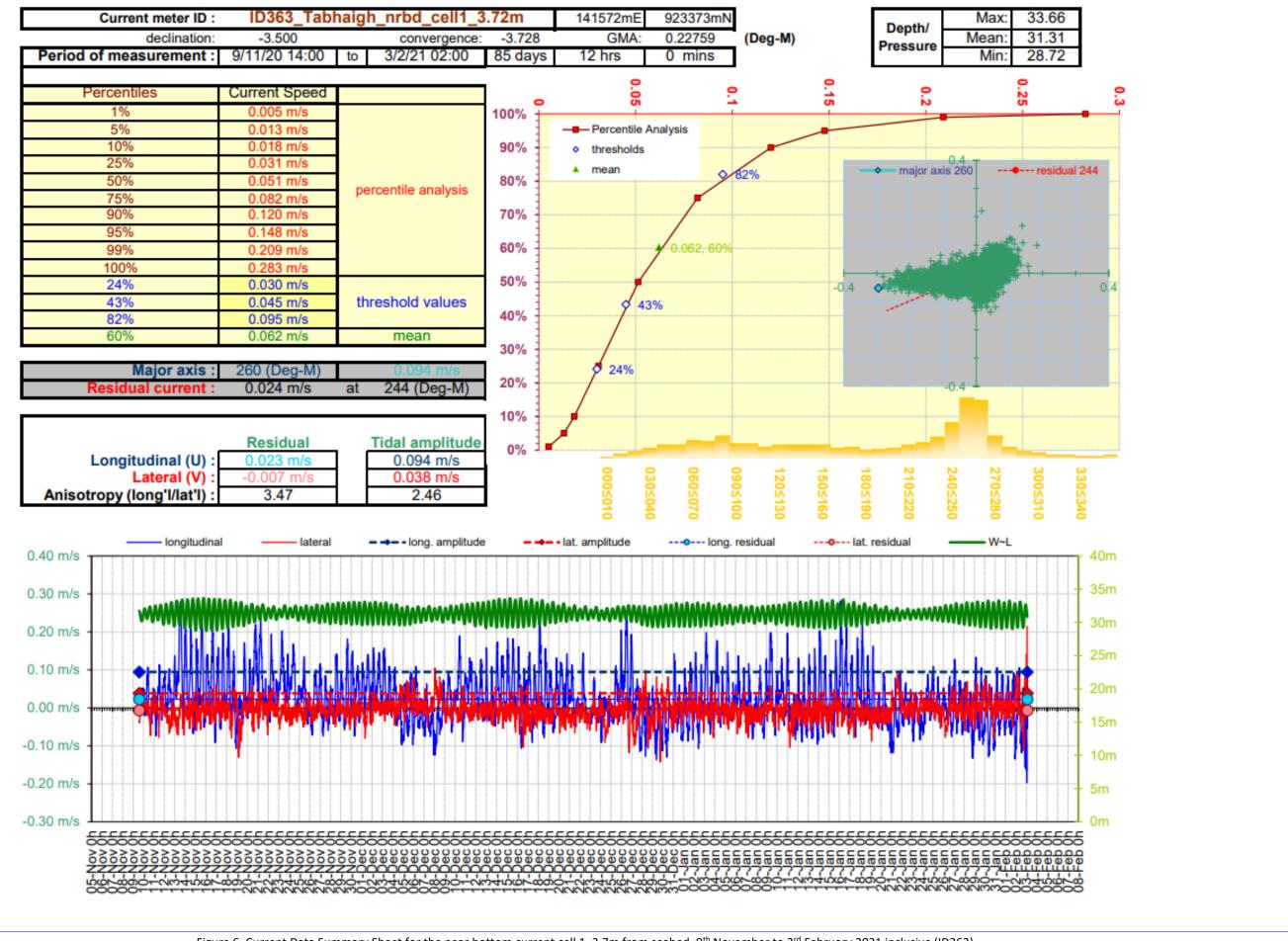


Figure 6. Current Data Summary Sheet for the near bottom current cell 1, 3.7m from seabed, 9<sup>th</sup> November to 3<sup>rd</sup> February 2021 inclusive (ID363).



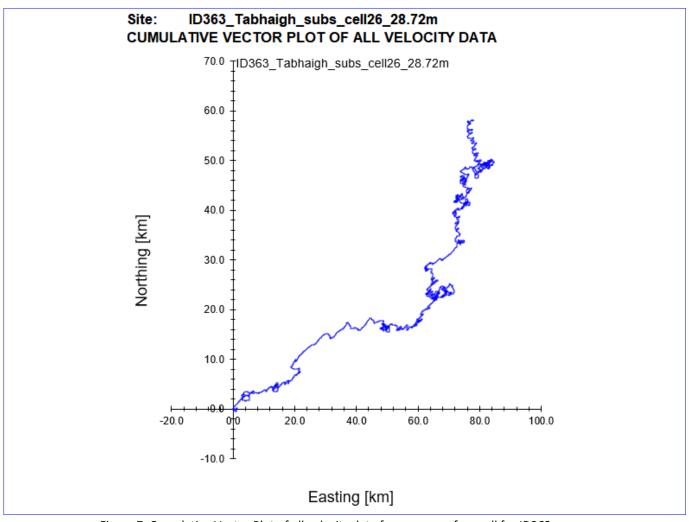


Figure 7. Cumulative Vector Plot of all velocity data from near surface cell for ID363.



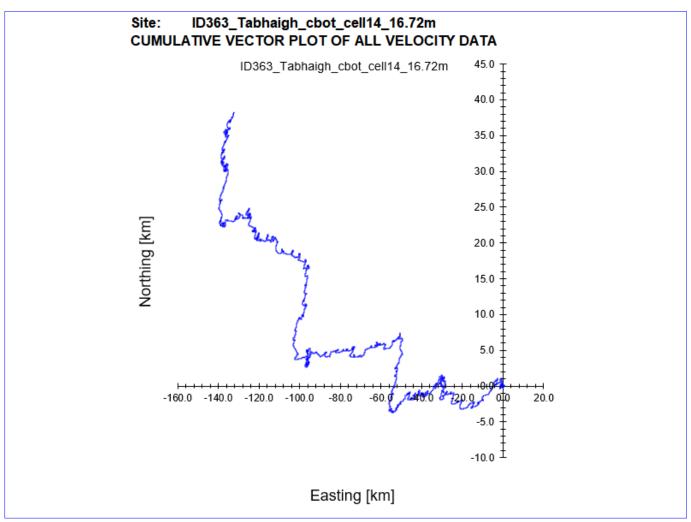


Figure 8. Cumulative Vector Plot of all velocity data from cage bottom cell for ID363.



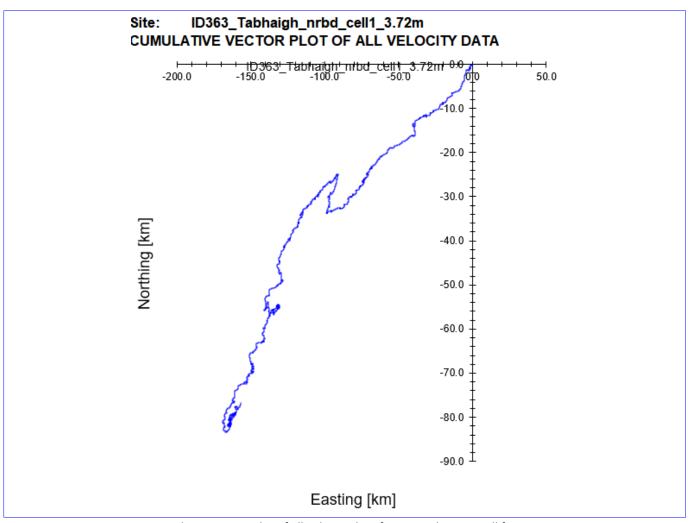


Figure 9. Cumulative Vector Plot of all velocity data from near bottom cell for ID363.



# 5. Summary of Current Data – ID363

Site Name: Tabhaigh
Data start date: 09/11/2020
Data end date: 03/02/2021
Mean Water Depth: 35.03 m

Table 2. Summary of current meter deployment

	Cell	Depth Below Surface (m)	Distance from Seabed (m)	Mean current speed (cm/s)
Near surface:	26	3.72	28.72	6.26
Cage bottom:	14	15.72	16.72	6.49
Near bed:	1	28.72	3.72	6.21
			Average current speed:	6.32

Table 3. Ranked percentiles for current speed at all three depths

Cell	Ranked Percentile (%) for mean speed	≤3cm/s (%)	≥4.5cm/s (%)	≥9.5cm/s (%)
Near surface:	57	18	63	17
Cage bottom:	59	22	59	21
Near bed:	60	24	47	18

Table 4. Major axis

rabie ii iiajei asiis				
Cell	Major Axis (Deg-G)			
Near surface:	075			
Cage Bottom:	260			
Near bed:	260			

Table 5. Mean and residual currents

Cell	Residual Speed (m/s)	Residual Parallel (m/s)	Residual Normal (m/s)	Tidal Amplitude Parallel (m/s)	Tidal Amplitude Normal (m/s)
Near Surface:	0.013	0.012	-0.005	0.089	0.048
Cage Bottom:	0.019	0.017	0.008	0.101	0.039
Near Bed:	0.024	0.023	-0.007	0.094	0.038





Figure 10. Summary of heading data from deployment ID363.

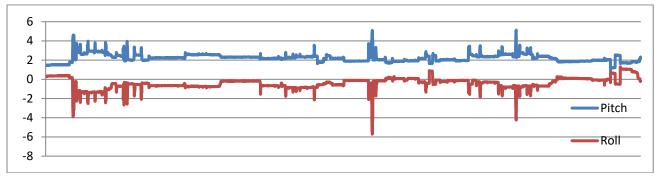


Figure 11. Summary of pitch and roll data from deployment ID363.

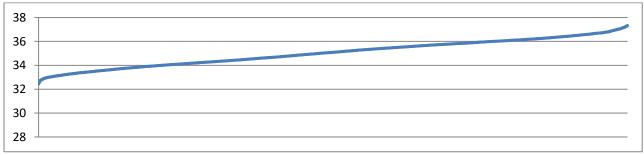


Figure 12. Pressure data from deployment ID363

#### 6. Conclusion

MOWI has collected and analysed current and bathymetric data for the salmon farm at Tabhaigh. The analysed current data for the 85 days and 12 hours period are believed to be reliable and representative of the proposed location. The bathymetric data from the ECLH bathymetry data and the local depth survey provided a coherent bathymetric dataset for the site.



### Annex 1. Survey Equipment Deployment Log

Location: Tabhaigh

Nearest tidal port: Loch Shell

Time zone: UTC

Meter switched on: 14:00 09/11/2020

Meter switched off: 02:00 03/02/2021

Period used for this report: 14:00 09/11/2020 - 02:00 03/02/2021

ADCP serial number: 24356

Meter position: 58.12352N, -6.39062W

141572 E 923373 N

Minimum water depth: 32.44 m (31.74 m measured by ADCP + 0.7 m \*)

Water depth (Chart Datum): 31.94 m (minimum water depth - 0.5 m tide timetable)

Mean water depth:  $35.73 \text{ m} (35.03 \text{ measured by ADCP} + 0.7 \text{ m}^*)$ 

Depth of meter from surface: 31.24 m (below chart datum to transducer)

Height of meter from seabed: 0.7 m to transducer head

Sounding at deployment: 33 m @ 09:45 on 09/11/2020

Table A1. ADCP meter settings:

Reference:	Transducer
Bin size (m):	1.0
Dist to 1 <sup>st</sup> bin (m):	3.02
Number of bins:	39
Frequency (kHz):	307
Recording interval (mins):	20
No. pings per ensemble:	300
Magnetic correction:	0
Ensemble:	300
Standard Deviation (cm/sec):	0.63
Time/Ping (seconds):	2