



CONTENTS

1.		6
2.	MATERIALS & METHODS	7
2.1	Depth Survey	7
2.2	Current Data	8
2.3	Magnetic Variation	10
2.4	Data Processing	10
2.5	Meteorological Survey	13
3.	RESULTS AND DISCUSSION	14
3.1	Deployment 1: 22 nd March – 4 th May 2017	14
3.2	Deployment 2: 5 th May – 3 rd July 2017	14
4.	HYDROGRAPHIC DATA SUMMARY SHEETS	15
5.	SUMMARY OF CURRENT DATA PART 1	20
6.	SUMMARY OF CURRENT DATA PART 2	27
7.	SUMMARY OF METEOROLOGICAL DATA	29
8.	CONCLUSION	29
ANNEX 1	SURVEY EQUIPMENT DEPLOYMENT LOGS	30



LIST OF FIGURES

Figure 1. Site location (top) and proposed pen setup (bottom).	6
Figure 2. Bathymetry survey - spot depth locations collected by Anderson Marine Surveys Ltd on behalf	of
Marine Harvest. Proposed cage locations are indicated (o).	7
Figure 3. Spot depths collected by Marine Harvest (left) combined with additional depth data (right).	
Proposed cage locations are indicated (o).	7
Figure 4. Model bathymetry in the region of the Macleans Nose site, as used with NewDepomod.	8
Figure 5. Positions of ADCP deployments in 2017 (▲). This report refers to the most northerly deployme	ent
location.	9
Figure 6. Mean beam intensity of the ADCP signal collected from 22 nd March – 4 th May 2017 plotted by	
depth (left) and cell (bin) number (right).	12
Figure 7. Mean beam intensity of the ADCP signal collected from 5 th May – 3 rd July 2017 plotted by dept	h
(left) and cell (bin) number (right).	12
Figure 8. Current Data Summary Sheet for surface current cell 30, 31.7m from seabed, 22 nd March – 4 th	
May 2017 inclusive.	15
Figure 9. Current Data Summary Sheet for cage bottom current cell 19, 20.7m from seabed, 22 nd March	-
4 th May 2017 inclusive.	16
Figure 10. Current Data Summary Sheet for surface current cell 1, 2.7m from seabed, 22^{nd} March – 4^{th} M	Иay
2017 inclusive.	17
Figure 11. Cumulative Vector Plot of velocity data from surface cell 30	18
Figure 12. Cumulative Vector Plot of velocity data from middle cell 19.	18
Figure 13. Cumulative Vector Plot of velocity data from bottom cell 1.	19
Figure 14. Graph of Heading of Workshorse Sentinel ADCP Current Meter during Deployment 1.	21
Figure 15. Graph of Pitch & Roll of Workhorse Sentinel ADCP Current Meter during Deployment 1.	21
Figure 16. Current Data Summary Sheet for surface current cell 30, 31.7m from seabed 5th May – 3rd Jul	ly
2017 inclusive.	22
Figure 17. Current Data Summary Sheet for cage bottom current cell 20, 21.7m from seabed, 5th May -	3 rd
July 2017 inclusive.	23
Figure 18. Current Data Summary Sheet for surface current cell 1, 2.7m from seabed, 5^{th} May – 3^{rd} July	
2017 inclusive.	24
Figure 19. Cumulative Vector Plot of velocity data from surface cell 30	25
Figure 20. Cumulative Vector Plot of velocity data from middle cell 20.	25
Figure 21. Cumulative Vector Plot of velocity data from bottom cell 1.	26
Figure 22. Graph of Heading of Workshorse Sentinel ADCP Current Meter during Deployment 2.	28
Figure 23. Graph of Pitch & Roll of Workhorse Sentinel ADCP Current Meter during Deployment 2.	28



LIST OF TABLES

Table 1. Workhorse Sentinel ADCP Specifications	11
Table 2. Selected cells and depths for the two deployments at Macleans Nose North	13
Table 3 Summary of current meter deployment	20
Table 4 Ranked percentiles for current speed at all three depths	20
Table 5 The mean and residual currents recorded	20
Table 6. Summary of current meter deployment.	27
Table 7. Ranked percentiles for current speed at all three depths	27
Table 8. The mean and residual currents recorded	27



QUALITY ASSURANCE

Marine Harvest (Scotland) Ltd is ISO9001 and ISO14001 accredited and all project management follows policies designed to ensure that the collection, collation and reporting of information produced in the course of our operations is done to a consistently high standard meeting the requirements of the end user.



1. Introduction

Marine Harvest (Scotland) Ltd is preparing an application to the planning authority and the Scottish Environmental Protection Agency (SEPA) to increase production at Macleans Nose salmon farming site. Marine Harvest (Scotland) Ltd proposes to install 16 pens, with 16m deep nets, which will be held in 75m grid, at an orientation of 160° (Figure 1). The maximum standing biomass likely to be applied for is 3,500 tonnes.

Marine Harvest (Scotland) Ltd staff carried out a hydrographic survey at the site during 2017. Hydrographic data at two sites ("Macleans Nose North" and "Macleans Nose South") were gathered during the period between 22nd March 2017 and the 3rd July 2017 in two deployments:

- 22nd March 4th May 2017 5th May 3rd July 2017 (i)
- (ii)

This report describes the data from both deployments at Maclean Nose South. The purpose of the report is to assess the suitability of the collected hydrographic data for input into a hydrodynamic model of the Macleans Nose region and also into the NewDepomod model.



Figure 1. Site location (top) and proposed pen setup (bottom).



2. Materials & Methods

2.1 Depth Survey

Bathymetry data for the study area was obtained by combining regional bathymetry with a local depth survey. Regional scale bathymetry was extracted from numerical models of the Scottish shelf, which utilised a variety of sources (e.g. digital bathymetry datasets, Admiralty charts and multibeam surveys). The regional scale bathymetry was supplemented by a local depth survey conducted by Anderson Marine Surveys Ltd in March 2017 (Figure 2). The local survey covered an area of *ca.* 2 km².



Figure 2. Bathymetry survey – spot depth locations collected by Anderson Marine Surveys Ltd on behalf of Marine Harvest. Proposed cage locations are indicated (o).

Measured depths ranged from -2.7 m in the inshore area to 100 m north-east of the cage group (Figure 3). These local data were merged with the regional scale bathymetry to generate a bathymetry map of the site area (Figure 4), which was consistent with expected values according to UK Admiralty data.



Figure 3. Spot depths collected by Marine Harvest (left) combined with additional depth data (right). Proposed cage locations are indicated (**o**).



Figure 4. Model bathymetry in the region of the Macleans Nose site, as used with NewDepomod.

2.2 Current Data

A Teledyne RDI Acoustic Doppler Current Profiler (Workhorse Sentinel ADCP) was used to record current data at Macleans Nose salmon farm. The Workhorse Sentinel ADCP was installed in a mooring frame with 20° free gimbal movement that automatically levels the instrument when deployed on the seabed. The Workhorse ADCP was a 300kHz medium range self-recording acoustic Doppler profiler which allows multiple simultaneous sampling strategies with site specific cell size. This allows measurement of current through the entire water column referenced to the instrument. Further details of the Workhorse ADCP can be found at:-

www.rdinstruments.com

The Workhorse Sentinel ADCP, within its mooring frame, was positioned at 56 40.975N, 006 02.617W (NM 52445 61885), which was 185m from the nearest shoreline and less than 150m from the centre of the proposed cage group (Figure 5). The transducer head was 70cm from the base of the mooring frame. The depth at the Sentinel ADCP position was 47.7 m at the time of deployment, giving a corrected depth of 45.0 m with respect to the Tobermory tide table.

Initial soundings were taken to establish the possible depth the Sentinel ADCP would be situated at during high tide and in order for the most appropriate cell size to be determined. The instrument was then configured on site immediately before deployment by means of communication using a laptop computer. The cell size was set at 1.0m and the number of cells 47.

Data was automatically written and stored to the internal memory within the Sentinel ADCP main body and then downloaded to computer after completion of the deployment period.

The distance to the near bed cell is automatically calculated based on the configuration settings of the instrument, using the following equation:

Distance to centre of first cell = ½ cell size+blanking distance+(Transmit+lag)/2



This is the distance from the transducer head to the centre of the first cell which equated to 2.71 m. For this deployment the blanking distance was 0.6m, the cell size was 1.0 m, the lag was 0.46 m and the Transmit was 1.36 m. This figure is added to the height of the transducer head to give the actual height of the centre of the first cell which gives a height of 2.71 m and this is within the SEPA criteria of 3 m.

Standard deviation has been assessed throughout the deployment to identify accurate and reliable data for near bed, middle (net depth) and surface cells using the following equation:

Cell StdDev = Instrument StdDev $\sqrt{Percentage Valid Pings/100 \times 300}$

The Instrument StdDev in the above equation is determined using the deployment settings when the meter is programmed, examples of the Standard Deviation values for different configurations are shown in



Table 1. This deployment had a cell size of 1.0m which equates to an Instrument single point StdDev of *ca.* 14.0cm/s (Table 1).



Figure 5. Positions of ADCP deployments in 2017 (▲). This report refers to the most southerly deployment location.

The Percentage of valid pings used to calculate Cell StdDev is derived using "Percentage Good" data which allows us to relate the Standard Deviation to the actual data gathered. The percent good data is available for 1,2,3 and 4 which represent the following:

Percent good 1 = % of good data computed from 3 Beams Percent good 2 = % of bad data due to more than 2 Beam bad Percent good 3 = % of bad data due to error velocity exceeded Percent good 4 = % of good data computed from 4 Beams

The data from Percent good 1 and 4, for the relevant cells, is exported from Velocity and added together, this gives the total percentage of valid pings. The total percentage of valid pings is then used to calculate how many of the 300 pings were used to determine the current speed which is in turn used to calculate Standard Deviation for those individual cells.

The method described has been used to calculate the Standard deviation throughout the deployment for the surface, middle and bottom cells; the average StdDev values for the surface middle and bottom was 0.64cm/s, 0.63cm/s and 0.63cm/s respectively which are all within the SEPA criteria of 2cm/s.

2.3 Magnetic Variation

No magnetic variation correction was made to the Sentinel ADCP during deployment, this was undertaken to the data after the instrument was recovered and data downloaded. The magnetic variation used was 3.51W; this was determined using the World Magnetic Model, produced jointly with the US National Oceanographic and Atmospheric Administration's National Geophysical Data center. Further details can be found at <u>http://www.geomag.bgs.ac.uk/navigation.html</u>



2.4 Data Processing

Upon retrieval of the Sentinel ADCP current meter, all data was downloaded to a computer for analysis. All raw data was opened in "Velocity" software and exported to Microsoft Excel. Pitch and roll data were analysed to identify that the deployment was successful. Once achieved the heading data was then observed to identify any movement of the Sentinel ADCP mooring frame during the deployment. Pitch and Roll were both less than 5° throughout the combined deployment period. Some transient disturbance to the instrument was evident on 24th May but this was short-lived and the pitch and roll values remained less than 4°. The heading did not exhibit any unexpected variation, with variations over the deployment period being less than 3°. On this basis, it was concluded that pitch, roll and heading were within a suitable range with variations throughout most of the deployment.

Depth data were then assessed and found to be valid when comparing against soundings taken at the time of current meter deployment.

Calculations were then undertaken to identify each cell to be used for surface and middle currents. Beam signal strength (intensity) was checked for interference (Figure 6 and Figure 7). During the first deployment, interference was evident in the beam intensity centred at a depth of 28.3 m (Figure 6. Mean beam intensity of the ADCP signal collected from 22^{nd} March – 4^{th} May 2017 plotted by depth (left) and cell (bin) number (right).Figure 6), perhaps due to a mooring line. Although the RDI ADCP is capable of calculating velocities using only three beams, the raw data suggest that the interference may have affected the velocity data shallower than 28 m. Therefore, although we will report the data here, it should be treated with some caution. Surface, middle and bottom data were taken from bins 37, 27 and 1 respectively, corresponding to depths of 6.3 m, 16.3 m and 42.3 m.

For the second deployment, the data from Bins 1 - 36 were good, with no indication of interference (Figure 7). Surface data were taken at -6.2 m (cell 36), and cage-bottom data at 16.2m (cell 26). Surface and middle cell heights were 37.7m and 27.7m from the seabed respectively. The bottom cell (Cell 1) was 2.7 m above the seabed at a depth of 41.2 m depth (Table 2).

Table 1. Workhorse Sentinel ADCP Specifications

Workhorse Sentinel



Self-Contained 1200, 600, 300 kHz ADCP

TECHNICAL SPECIFICATIONS

Water Profiling	Depth Cell Size ¹	Typical Ran 1200kHz	ge ¹ 12m		Typical Rar 600kHz	ige ¹ 50m	Typical Rar 300kHz	nge ^o 110m
	Vertical Resolution 0.25m	Range ³ 11m	Std. Dev. 14.0cm/	4	Range ⁵	Std. Dev.*	Range ³	Std. Dev.*
	0.5m	12m	7.0cm/s		38m	14.0cm/s	see note 1	
	1m	13m	3.6cm/s		42m	7.0cm/s	83m	14.0cm/s
	2m	15m²	1.8cm/s		46m	3.6cm/s	93m	7.0cm/s
	4m	see note 1			51m ²	1.8cm/s	103m	3.6cm/s
	8m						116m ²	1.8cm/s
Long Range Mode	2m	19m	3.4m/s					
	4m				66m	3.6cm/s		
	8m						154m	3.7cm/s
Profile Parameters	Velocity accuracy	0.3% of the relative to /	water velo ADCP ±0.3c	icity m∕s	0.3% of the relative to	e water velocity ADCP ±0.3cm/s	0.5% of the relative to	e water velocity ADCP ±0.5cm/s
	Velocity resolution	0.1cm/s			0.1cm/s		0.1cm/s	
	Velocity range:	±5m/s (defa	ault) ±20m/	s (max)	±5m/s (def	ault) ±20m/s (max)	±5m/s (def	fault) ±20m∕s (max)
	Number of depth cells	1-255			1-255		1-255	
	Ping rate	Up to 10Hz	1		Up to 10Hz	z	Up to 10H	z
Echo Intensity Profile	Vertical resolution			Depth cel	l size, user co	nfigurable		
	Dynamic range			80dB				
	Precision			±1.5dB				
Transducer and Hardware	Beam angle			20°				
	Configuration			4-beam, o	onvex			
	Internal memory			Two PCM	CIA card slots	; one memory card inc	luded	
	Communications			K2-232 0	r KS-422;ASI	LII or binary output at	1200-115,20	J baud
Power	DC input			20-50VD	C			
	Number of patteries			A TYPE (m	w) 29VDC (4	(notoch)		
	Rattery canacity (70.0°C			450 watt	hrs	epteteuj		
6 I II	battery capacity (pro c			-50 mail				
Standard Sensors	Tilt	uansoucer)		Range - 51 Range ±1	* to 45°C, Pre 5° Arrurary ±	cision #0.4°C, Resoluti :0.5° Precision ±0.5°	on 0.01* Resolution 0.0	1*
	Compass fluxoare type. Inc	ludes		in the second	, increased			-
	built-in field calibration feat	ure)		Accuracy #	±2° ³ , Precision	n ±0.5°°, Resolution 0.	01°, Maximum	n tilt ±15°
Environmental	Standard depth rating			200m; op	tional to 500	m, 1000m, 6000m		
	Operating temperature			-5° to 45°	°C			
	Storage temperature (with	iout batteries)		-30° to 60	rc			
	Weight in air			13.0kg				
	weight in water			4.5NJ				
Software	TRDI's Windows ^{IN} based	software inclu	ded: WinSC	C—Data Acq	uisition Syste	em; WinADCP – Data D	isplay and Ex	port
Available Options	Memory: 2 PCMCIA slot	s, total 4GB •	Pressure se	nsor • Exte	mal battery o	ase • High-resolution	water-profilin	ig modes
	 Bottom tracking or surface 	ace referencin	g track • AC	/DC power	converter, 48	NUC output • Pressure	e cases for dep	pths up to 6000m
	Directional Wave Array	 Acoustic Mod 	dem • Indu	ctive Moder	m • Velocity i	for advanced post proc	ressing	
Dimensions	228.0mm wide x 405.5m	m long (line d	tawings ava	ailable upor	n request)			
1. User's choice of skeeth cell size is not limited to a	to protect values specified.							

Longer ranges available.
 Longer ranges available.
 Longer ranges available.
 SetUling approximation on the percurve values at SYC and 20°C, salinity- 35ppc.
 BroadBand mode strajio ping scandard deviation (Sci. Dev.)
 S -+1.0° is commonly achieved after calibration.





Figure 6. Mean beam intensity of the ADCP signal collected from 22nd March – 4th May 2017 plotted by depth (left) and cell (bin) number (right).



Figure 7. Mean beam intensity of the ADCP signal collected from 5th May – 3rd July 2017 plotted by depth (left) and cell (bin) number (right).



Table 2. Selected cells and depths for the two deployments at Macleans Nose North

Deployment Date	Water Depth (m)		Cell Number	Cell Depth (m)
		Surface	37	6.3
22 nd March – 4 th May	45.0	Middle	27	16.3
2017		Bottom	1	42.3
		Surface	36	6.2
5 th May – 3 rd July 2017	43.9	Middle	26	16.2
		Bottom	1	41.2

2.5 Meteorological Survey

Meteorological data were not collected during this survey.



3. Results and Discussion

3.1 Deployment 1: 22nd March – 4th May 2017

A summary of the current data is shown in Figure 8 – Figure 15 and in Table 3 – Table 5. Over the 43 days analysed for this report, the surface, middle and bottom cells had averages of 7.7 cm/s, 6.2 cm/s and 5.6 cm/s respectively. This gave an overall average of 6.5 cm/s. The orientation of the tidal velocities at the surface and middle was northwest to southeast, consistent with a flow parallel to the shoreline; at the bottom, the orientation was north-south.

The residual currents for the bottom, middle and surface cells are similar, with mean values of 1.0 cm/s, 3.1 cm/s and 4.4 cm/s respectively. The direction of the residual current at the surface was to the northwest. The weak residual at the seabed was to the south-southeast.

The depth records shown by the current meter pressure sensor exhibited a very clear spring-neap tidal cycle, with a spring range of about 4.5 m and a neap range of about 1.0 - 1.5 m.

3.2 Deployment 2: 5th May – 3rd July 2017

A summary of the current data is shown in Figure 16 – Figure 23 and in Table 6 – Table 8. Over the 59 days analysed for this report, the surface, middle and bottom cells had averages of 6.6 cm/s, 5.2 cm/s and 5.0 cm/s respectively. This gave an overall average of 5.6 cm/s. The orientation of the tidal velocities at the surface and middle was northwest to southeast, consistent with a flow parallel to the shoreline; at the bottom, the orientation was north-south.

The residual currents for the bottom, middle and surface cells were similar, with mean values of 0.4 cm/s, 2.5 cm/s and 3.7 cm/s. The direction of the residual current was west-northwest at the surface and middle depths and south-southwest at the bottom.

The depth records shown by the current meter pressure sensor exhibited a very clear spring-neap tidal cycle, with a spring range of about 4 m and a neap range of about 1.5 m.

4. Hydrographic Data Summary Sheets



Figure 8. Current Data Summary Sheet for surface current cell 37, 38.7m from seabed, 22nd March – 4th May 2017 inclusive.

х	у		
major a	xis 340		
-0.137	0.3759		
-0.036	0.0989		
0	0		
######	######		
residual 326			
0	0		
-0.024	0.0363		
-0.221	0.3335		



Figure 9. Current Data Summary Sheet for cage bottom current cell 27, 28.7m from seabed, 22nd March – 4th May 2017 inclusive.



8	
х	у
major a	xis 335
-0.085	0.1813
-0.036	0.0775
0	0
######	######
residu	al 330
0	0
-0.015	0.0265
-0.1	0.1731



Figure 10. Current Data Summary Sheet for surface current cell 1, 2.7m from seabed, 22nd March – 4th May 2017 inclusive.

Х	у
major a	xis 190
-0.035	-0.197
-0.015	-0.086
0	0
######	######
residu	al 157
0	0
0.0038	-0.009
0.0765	-0.185



Figure 11. Cumulative Vector Plot of velocity data from surface cell 37



Figure 12. Cumulative Vector Plot of velocity data from middle cell 27.



Figure 13. Cumulative Vector Plot of velocity data from bottom cell 1.



5. Summary Of Current Data Part 1

Site Name: Macleans Nose

Data start date:22nd March 2017Data end date:4th May 2017

Water Depth (CD): 45.0 m

Table 3	Summary	of current	meter de	ployment
---------	---------	------------	----------	----------

Cell	Mean Cell Height from seabed (m)	Mean cell depth below surface (m)	Cell Size (m)	Mean Current Speed (cm/s)	Ranked Percentile (%) for mean speed
Тор	38.7	6.3	1	7.70	59
Middle	28.7	16.3	1	6.18	59
Bottom	2.7	42.3	1	5.56	57

 Table 4
 Ranked percentiles for current speed at all three depths

Cell	≤3cm/s (%)	≥4.5cm/s (%)	≥9.5cm/s (%)
Тор	14	72	29
Middle	23	59	19
Bottom	27	56	14

Cell	Major Axis (Deg-G)
Тор	340
Middle	335
Bottom	190

Table 5 The mea	an and residual	currents recorded
-----------------	-----------------	-------------------

	Mean Speed (m/s)	Residual Speed (m/s)	Residual Parallel (m/s)	Residual Normal (m/s)	Tidal Amplitude Parallel (m/s)	Tidal Amplitude Normal (m/s)
Surface	0.077	0.044	0.042	-0.010	0.105	0.042
Middle	0.062	0.031	0.030	-0.003	0.086	0.041
Bottom	0.056	0.010	0.008	-0.005	0.087	0.028



Figure 14. Graph of Heading of Workhorse Sentinel ADCP Current Meter during Deployment 1.



Figure 15. Graph of Pitch & Roll of Workhorse Sentinel ADCP Current Meter during Deployment 1.



Figure 16. Current Data Summary Sheet for surface current cell 36, 37.7m from seabed 5th May – 3rd July 2017 inclusive.



х	с у				
major a	ixis 335				
-0.127	0.2719				
-0.039	0.0828				
0	0				
######	######				
residu	residual 320				
0	0				
-0.024	0.0288				
-0.191	0.2315				



Figure 17. Current Data Summary Sheet for cage bottom current cell 26, 27.7m from seabed, 5th May – 3rd July 2017 inclusive.



-	
х	у
major a	xis 325
-0.115	0.1638
-0.04	0.0577
0	0
######	######
residu	al 323
0	0
-0.015	0.0196
-0.122	0.1587



Figure 18. Current Data Summary Sheet for surface current cell 1, 2.7m from seabed, 5th May – 3rd July 2017 inclusive.

Х	У			
major a	xis 185			
-0.017	-0.199			
-0.007	-0.077			
0	0			
######	######			
residu	al 200			
0	0			
-0.001	-0.004			
-0.067	-0.188			



Figure 19. Cumulative Vector Plot of velocity data from surface cell 36



Figure 20. Cumulative Vector Plot of velocity data from middle cell 26.



Figure 21. Cumulative Vector Plot of velocity data from bottom cell 1.

marineharv

6. Summary Of Current Data Part 2

Site Name: Macleans Nose

Data start date:5th May 2017Data end date:3rd July 2017

Water Depth (CD): 43.9 m

Table 6. Summary of current meter deployment.

Cell	Mean Cell Height from seabed (m)	Mean cell depth below surface (m)	Cell Size (m)	Mean Current Speed (cm/s)	Ranked Percentile (%) for mean speed
Тор	37.7	6.2	1	6.6	59
Middle	27.7	16.2	1	5.2	58
Bottom	2.7	41.2	1	5.0	55

Table 7. Ranked percentiles for current speed at all three depths

Cell	≤3cm/s (%)	≥4.5cm/s (%)	≥9.5cm/s (%)
Тор	22	61	23
Middle	29	51	10
Bottom	29	53	8

Cell	Major Axis (Deg-G)
Тор	335
Middle	325
Bottom	185

Table 8. The mean and residual currents recorded

	Mean Speed (m/s)	Residual Speed (m/s)	Residual Parallel (m/s)	Residual Normal (m/s)	Tidal Amplitude Parallel (m/s)	Tidal Amplitude Normal (m/s)
Surface	0.066	0.037	0.036	-0.009	0.091	0.033
Middle	0.052	0.025	0.025	-0.001	0.070	0.035
Bottom	0.050	0.004	0.004	0.001	0.077	0.026



Figure 22. Graph of Heading of Workshorse Sentinel ADCP Current Meter during Deployment 2.



Figure 23. Graph of Pitch & Roll of Workhorse Sentinel ADCP Current Meter during Deployment 2.

7. Summary Of Meteorological Data

No meteorological data were collected.

8. Conclusion

Marine Harvest (Scotland) Ltd has collected and analysed current and bathymetric data for the Macleans Nose salmon farm site. Two deployments were made at the Macleans Nose South site, totalling 102 days of data.

The analysed current data for the first deployment period, from 22^{nd} March – 4^{th} May 2017, was consistent with the second deployment, but there was evidence of interference in one of the instrument beams which may have contaminated the data. The data should therefore be used with caution.

The analysed current data for the for the second deployment period, from 5^{th} May – 3^{rd} July 2017, exhibit no signs of beam interference and are believed to be reliable and representative of the proposed location.

Meteorological data were not collected.

The bathymetric data gained from surveying the proposed site proved to be representative of chart data for the same location.

It is therefore concluded this complete data set is acceptable for use in calibrating a hydrodynamic model of the area and for use with NewDepomod.

Sentinel V (ADCP) Current Meter Record Log

Location:	MacLean's Nose		
Nearest tidal port:	Tobermory	Time zone: UTC	

Max spring / min neap range during deployment:

	Date	Time	Height (m)
HW Spring tide	28/03/2017	05:59	4.8
Spring tide	26/04/2017	11:56	0.4
HW	19/04/2017	10:41	3.2
LW	19/04/2017	17:29	2.0

Deployment Details

	Time			Date
Meter switched on.	13:15:03		22/03/2017	
Meter deployed.	13:15:03		22/03/2017	
Meter lifted.	19:15:03		04/05/2017	
Meter switched off.	19:15:03		04/05/2017	
Period used for this report.	22/03/2017 13:15:03	to	C	04/05/2017 15:15:03

ADCP serial number:	24614
Meter position:	56° 40.975N 006° 02.617W
	152445.1E, 761885.09N
Minimum water depth:	45.0m (44.3m measured by ADCP + 0.7m *)
Water depth (Chart Datum):	44.6m (minimum water depth – 0.4m tide timetable)
Mean water depth:	47.4m (measured by ADCP + 0.7m *)
Depth of meter from surface:	44.3m (below mean low water spring to transducer)
Depth of meter from seabed:	* Meter on seabed 0.7m to transducer head
Sounding at deployment:	47.7m @ 13:15 on 22/03/2017
Corrected sounding:	44.6 m (47.7m – 3.1m from Tobermory table)

Data summary:

	<u>Cell number</u>	<u>Depth (m)</u>	Dist from seabed (m)	<u>Mean current</u> speed (cm/s)
Surface	Cell 37	6.3m Below MLWS	38.7m	7.70
Mid depth	Cell 27	16.3m Below MLWS	28.7m	6.18
Bottom	Cell 1	42.3 m Below MLWS	2.7m	5.56
Average	e current speed:			6.5



ADCP meter settings:

Reference	Transducer
Bin size	1.0m
Dist to 1 st bin	2.02
Number of bins	44
Frequency	307 kHz
Recording interval	20 min
No. pings per ensemble	300
Magnetic correction	0
Ensemble	300
Standard Deviation	0.63cm/sec
Time/Ping	00:01:00

Sentinel V (ADCP) Current Meter Record Log

Time zone: UTC

Location:	
-----------	--

Nearest tidal port:

MacLean's Nose

Tobermory

Max spring / min neap range during deployment:

	Date	Time	Height (m)
HW HW	25/05/2017	05:09	4.7
LW	25/05/2017	11:31	0.5
HW HW	19/05/2017	11:41	3.2
LW	19/05/2017	18:02	1.9

Deployment Details

	Time			Date
Meter switched on.	08:17:24		05/05/2017	
Meter deployed.	08:17:24			05/05/2017
Meter lifted.	12:17:24			03/07/2017
Meter switched off.	12:17:24		03/07/2017	
Period used for this report.	05/05/2017 08:09:24	to	С	03/07/2017 09:57:24

ADCP serial number:	24614
Meter position:	56° 40.986N 006° 02.620W
	152443.25E, 761905.66N
Minimum water depth:	43.9m (43.2m measured by ADCP + 0.7m *)
Water depth (Chart Datum):	43.5m (minimum water depth $-$ 0.4m tide timetable)
Mean water depth:	46.2m (measured by ADCP + 0.7m *)
Depth of meter from surface:	43.2m (below mean low water spring to transducer)
Depth of meter from seabed:	* Meter on seabed 0.7m to transducer head
Sounding at deployment:	45.3m @ 08:17 on 05/05/2017
Corrected sounding:	42.2 m (45.3m – 3.1m from Tobermory table)

Data summary:

	<u>Cell number</u>	<u>Depth (m)</u>	Dist from seabed (m)	<u>Mean current</u> speed (cm/s)
Surface	Cell 36	6.2m Below MLWS	37.7m	6.56
Mid depth	Cell 26	16.2m Below MLWS	27.7m	5.16
Bottom	Cell 1	41.2m Below MLWS	2.7m	5.04
Average	current speed:			5.6



ADCP meter settings:

Reference	Transducer
Bin size	1.0m
Dist to 1 st bin	2.02
Number of bins	44
Frequency	307 kHz
Recording interval	20 min
No. pings per ensemble	300
Magnetic correction	0
Ensemble	300
Standard Deviation	0.63cm/sec
Time/Ping	00:01:00